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Logic and Computation: I Chapter 2 Propositional logic and computational complexity

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– Logic and Computation I

- Part 1. Introduction to Theory of Computation
- Part 2. Propositional Logic and Computational Complexity
- Part 3. First Order Logic and Decision Problems

- Part 2. Schedule

- Nov.17, (1) Tautologies and proofs
- Nov.22, (2) The completeness theorem of propositional logic
- Nov.24, (3) SAT and NP-complete problems
- Nov.29, (4) NP-complete problems about graphs
- Dec. 1, (5) Time-bound and space-bound complexity classes
- Dec. 6, (6) PSPACE-completeness and TQBF



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NP-complete problems about graphs

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- A Yes/No problem belongs to P if there exists a **deterministic** TM and a polynomial p(x) s.t. for an input string of length n, it returns the correct answer within p(n) steps.
- A problem belongs to NP if there is a **nondeterministic** TM and a polynomial p(x) s.t. for an input string of length n, it always stops within p(n) steps and answers
 - $\triangleright\,$ Yes, if at least one accepting computation process admits it;
 - \triangleright No, if all the computation processes reject.
- Q_1 is polynomial (time) reducible to Q_2 , denoted as $Q_1 \leq_p Q_2$, if there exists a polynomial-time algorithm A which solves a problem q_1 in Q_1 as problem $A(q_1)$ in Q_2 .
- Q is NP-hard if for any NP problem Q', $Q' \leq_p Q$.
- An NP-hard NP problem is said to be NP-complete.

Theorem

The Cook-Levin theorem: SAT is NP-complete.

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Recap Introduction Vertex cover Hamiltonian of Summary We also showed the satifiablity problem ${\rm SAT}$ restricted to some special Boolean formulas remains NP-complete.

- A variable x and its negation ¬x are called literals. A disjunction (∨) of literals is called a clause. A conjunction (∧) of clauses is called a CNF (conjunctive normal form).
- **CNF-SAT** is the satisfiability problem for conjunctive normal forms.

Theorem

CNF-SAT is NP-complete.

• A CNF with exactly 3 literals in each clause is called a **3-CNF**. **3-SAT** is the satisfiability problem for 3-CNF.

Theorem

 $\operatorname{3-SAT}$ is NP-complete.

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Recap Introduction Vertex cover Hamiltonian cy Summary Proof.

- To show CNF-SAT \leq_p 3-SAT, let ϕ be a CNF formula.
- If ϕ has a clause $l_1 \vee \cdots \vee l_k (k \geq 4)$, replace it with the following:

$$\begin{split} &(l_1 \vee l_2 \vee x_1) \wedge (l_3 \vee \bar{x}_1 \vee x_2) \wedge (l_4 \vee \bar{x}_2 \vee x_3) \wedge \dots \wedge (l_{k-2} \vee \bar{x}_{k-4} \vee x_{k-3}) \wedge (l_{k-1} \vee l_k \vee \bar{x}_{k-3}) \\ & \text{where } \bar{x} \text{ represents } \neg x. \end{split}$$

• For a clause with only one literal l_1 , replace it with

 $(l_1 \vee x_1 \vee x_2) \wedge (l_1 \vee x_1 \vee \bar{x}_2) \wedge (l_1 \vee \bar{x}_1 \vee x_2) \wedge (l_1 \vee \bar{x}_1 \vee \bar{x}_2).$

• For a clause with only two literals $l_1 \lor l_2$, replace it with

 $(l_1 \lor l_2 \lor x_1) \land (l_1 \lor l_2 \lor \bar{x}_1).$

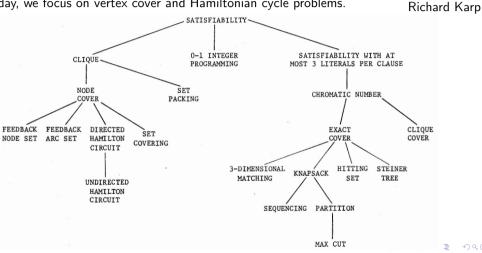
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- It is easy to see that the satisfiability condition does not change by these transformations.
- Since the above transformations can be performed by polynomial-time algorithms, CNF-SAT is polynomial-time reducible to 3-SAT.

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- Introduction

- Following Cook's work on SAT, in 1972 R. Karp published a list of 21 NP-complete problems. In addition to 3-SAT, there are Hamiltonian cycle problem, graph coloring problem, knapsap problem.
- Today, we focus on vertex cover and Hamiltonian cycle problems.





Source: R. Karp (1972) Reducibility Among Combinatorial Problems



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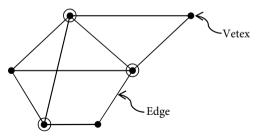
Definition

A directed graph G = (V, E) consists of a set of vertices V and a set of edges $E \subseteq V \times V$. A graph such that $(u, v) \in E \Leftrightarrow (v, u) \in E$ is called an undirected graph.

Here we only consider finite graphs.

Definition

A vertex cover of an undirected graph G = (V, E) is a subset $S \subseteq V$ of vertices such that for any edge $(u, v) \in E$ of G, $u \in S$ or $v \in S$.



The set of \odot is the vertex cover. Every edge has one endpoint in the vertex cover \odot

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Definition

- The vertex cover problem VC: Given an undirected graph G and a natural number k, decide whether there exists a vertex cover S of G consisting of k vertices.
- The problem of finding the minimum vertex cover size k for an undirected graph G is called **minimum vertex cover problem**.

Theorem

The vertex cover problem for undirected graphs is NP-complete.

– Consider to input G=(V,E) to the TM \cdot

- If the cardinality of V is n, E can be represented by an $n \times n$ matrix with components 0, 1, which is called **adjacency matrix**. Then graph G can be represented by a 0, 1 sequence of length n^2 .
- Thus, a polynomial size of the graph G can be regarded as a polynomial of V.

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- Choose a arbitrary set ${\cal S}$ of k vertices and check whether it is a vertex cover.
- It is easy to decide (in polynomial time) whether S is a vertex cover, since we only need to check that for each edge, one of its endpoints belongs to S.

- 3-SAT \leq_p VC

VC is an NP problem

Proof.

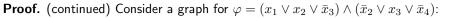
- Consider a 3-CNF formula $\varphi = \bigwedge_{j \leq m} (l_1^j \vee l_2^j \vee l_3^j).$
- Let $\{x_1, \ldots, x_n\}$ be the variables in φ . That is, l_1^j $(j \le m, s \le 3)$ is x_i or $\overline{x_i}$.

- Then construct the graph ${\cal G}=(V,E)$ such that
 - $V = \{x_i, \bar{x}_i : i \leq n\} \cup \{L_1^j, L_2^j, L_3^j : j \leq m\},\$

•
$$E = \{(x_i, \bar{x}_i) : i \le n\} \cup \{(L_1^j, L_2^j), (L_2^j, L_3^j), (L_3^j, L_1^j) : j \le m\} \cup \{(l_s^j, L_s^j) : j \le m, s \le 3\}.$$

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- \bar{x}_1 \bar{x}_2 \bar{x}_2 \bar{x}_3 \bar{x}_3 \bar{x}_3 \bar{x}_4 \bar{x}_4 Check whether there is a v.c. S of size k = n + 2m for the graph thus constructed $(k = 8 \text{ for } \varphi)$. • A v.c. must contain x_i or \bar{x}_i for each $i \le n$ and at least two of L_1^j, L_2^j, L_3^j . for each $j \le m$. • Hence, a v.c. of size k = n + 2mwill contain exactly one of x_i or \bar{x}_i and exactly two of L_1^j, L_2^j, L_3^j .
- Namely, one of L_1^j, L_2^j, L_3^j is not in S, and it must connect with either x_i or \bar{x}_i in S.
- Now, put $V(x_i) = T$ if $x_i \in S$, and $V(x_i) = F$; otherwise, $V(l_1^j \vee l_2^j \vee l_3^j) = T$ for all j and so $V(\varphi) = T$.
- Conversely, suppose there is a V such that $V(\varphi) = T$. We construct a v.c. S of size n + 2m. First, put x_i (or \bar{x}_i) into S if $V(x_i) = T$ (or $V(\bar{x}_i) = T$). Then at least one of L_1^j, L_2^j, L_3^j connects to x_i or \bar{x}_i in S. Except one of such, put the other two in S.

- In short, φ is satisfiable \Leftrightarrow the graph has a vertex cover of size k = n + 2m
- That is, 3-SAT is polynomial-time reducible to VC.



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Hamiltonian cycles

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Only finite connected graphs are considered.

Recall: Eulerian cycles in an undirected graph

- A **Eulerian path** passes through every edge exactly once. A **Eulerian cycle** is a Eulerian path whose start and end points coincide.
- An Eulerian cycle exists iff the degree of each vertex is even.

- A Hamiltonian cycle is a cycle passing through every vertex exactly once.
- There is no known simple criterion for the existence of Hamiltonian path.
- R. Karp showed that this problem is NP-complete and clarified it is difficult in principle to find such a criterion.

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Definition

Directed Hamiltonian cycle problem (dHAMCYCLE): for a directed connected graph, decide whether there is a Hamiltonian cycle (passing every vertex exactly once, following the direction of the edges)

Theorem

 $\operatorname{dHAMCYCLE}$ is NP-complete.

Proof. To show $dHAMCYCLE \in NP$, choose an arbitrary path of the directed graph and check whether it is a Hamiltonian cycle.

For its NP-completeness, we prove that VC is polynomial reducible to it.

• Assume an undirected graphs G = (V, E) and k. We construct a directed graph $G^* = (V^*, E^*)$.

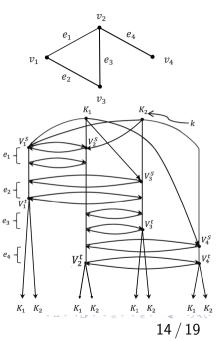
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- We show the following are equivalent:
 - $\triangleright~G^*$ has a Hamiltonian cycle.
 - \triangleright G has a vertex cover of size k.

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Recap Introduction Vertex cover Hamiltonian cycle Summary **Proof.** (VC \leq_p dHAMCYCLE, continued) Consider the graph G in the right figure with k = 2. The construction of G^* :

- \triangleright For k = 2, two points K_1, K_2 are fixed at the top.
- $\triangleright \ \ \text{Since} \ \ G \ \ \text{consists of 4 vertices} \ v_i(i=1,2,3,4) \text{, 4} \\ \text{downward lines} \ \overrightarrow{V_i^s V_i^t} \ \text{are drawn}.$
- ▷ If there is an edge between v_i and v_j in G, then a pair of double bridges are built so that it can go back and forth between $V_i^{s}V_i^{t}$ and $V_j^{s}V_j^{t}$.
- \triangleright Finally, draw a line from each K_l to each V_i^s and from each V_i^t to each K_l .
- In a Hamiltonian cycle on G^* , if a vertex V_i^s has an edge from a point K_l , then v_i is in the vertex cover of G.
- Since there are only m = 2 upper points K_l , there are exactly m such v_i 's, i.e., the size of the vertex cover corresponding to the Hamiltonian cycle is always 2.

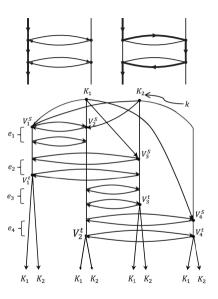


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Proof. (VC \leq_p dHAMCYCLE, continued)

- From the selected vertex V_i^s , go down toward V_i^t in one of the two ways shown in the right figures (straight and detour).
- Consider a Hamiltonian cycle C entering V_i^s from K_1 .
- If C does not include the edge from K_2 to $V_j^s(j \neq i)$ and there is a bridge between $\overline{V_i^s V_i^t}$ and $\overline{V_j^s V_j^t}$, C detours from $\overline{V_i^s V_i^t}$ to $\overline{V_j^s V_j^t}$ and returns to $\overline{V_i^s V_i^t}$. Otherwise, go down straight.
- If C makes a detour, just one end of the corresponding edge belongs to the vertex cover; otherwise, both endpoints are in the vertex cover.
- In any case, if G* has a Hamiltonian cycle, the set of vertices v_i such that V^s_i connects with some K_l is a vertex cover of k vertices.
 That is,



G has a vertex cover of size $k \Leftrightarrow G^*$ has a Hamiltonian cycle $\rightarrow \langle \sigma \rangle \land \langle \sigma \land \langle \sigma \rangle \land \langle \sigma \land \langle \circ \land \langle \sigma \land \langle \sigma \land \langle \circ \land$

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Proof. (VC \leq_p dHAMCYCLE, continued)

- The above argument can be generalized to any graphs. We omit this routine work.
- Although G^* looks much larger than G, it can be obtained by a polynomial-time algorithm. In fact, the number of vertices of G^* is a constant multiple of the number of edges of G.

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 $\bullet\,$ That is, VC is polynomial-time reducible to dHAMCYCLE.

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From this result, we can also show that decision problem on the existence of Hamiltonian cycles for undirected graphs is NP-complete.

Homework

Show that the decision problem of the existence of Hamiltonian cycles for undirected graphs ($\rm HAMCYCLE$) is NP-complete.

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- The Traveling Salesman Problem (TSP) is a variation of the Hamiltonian cycle problem.
 - A weight (distance) assigned for each edge of an undirected graph.
 - Is it possible to traverse all the points so that the sum of the weights of the passed edges does not exceed a given limit k?
 - Equivalently, does there exist a Hamiltonian cycle such that the sum of edge weights is less than or equal to k?

It can be shown that $\operatorname{TSP}\!$ is also NP-complete.

- $\bullet\,$ For TSP to be NP, choose an arbitrary path and check whether it satisfies the condition or not.
- For the reversal, the existence of a Hamiltonian cycle is the existence of a TSP solution with edge weight 1 and sufficiently large k, and so

HAMCYCLE \leq_p TSP.

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Summary

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• We have shown that the vertex cover problem VC and the directed Hamiltonian cycle problem dHAMCYCLE are NP-complete.

Further readings

 $\mathsf{M}.$ Sipser, Introduction to the Theory of Computation, 3rd ed., Course Technology, 2012

Thank you for your attention!