

# Logic and Computation II

## Part 6. Automata on infinite objects

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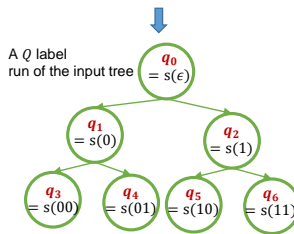
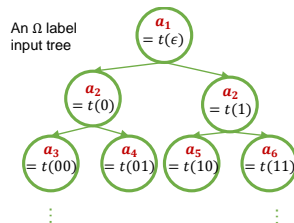
- **Part 4. Modal logic**
- **Part 5. Modal  $\mu$ -calculus**
- **Part 6. Automata on infinite objects**
- **Part 7. Recursion-theoretic hierarchies**

## Part 6. Schedule (tentative)

- Apr.15, (1) Second-order arithmetic and analytical hierarchy
- Apr.17, (2) Büchi automata
- Apr.22, (3) Safra's theorem
- Apr.24, (4) The decidability of S1S
- May 6, (5) Tree automata
- **May 8, (6) The decidability of S2S**
- May 13, (7) Finite model theory
- May 15, (8) Parity games

- An ( $\Omega$ -)**labeled tree** is the complete binary tree  $\{0, 1\}^*$  with each vertex labeled by a symbol in  $\Omega$ . It can be viewed as a function  $t : \{0, 1\}^* \rightarrow \Omega$ .
- The **tree automaton**  $M = (Q, \Omega, \delta, Q_0, Acc)$ :
  - $Q$ : a set of states,
  - $\delta \subseteq Q \times \Omega \times Q^2$ : a transition relation,
  - $Q_0 \subseteq Q$ : a set of initial states, and
  - $Acc$ : an acceptance conditions.
- For an **input  $\Omega$ -labeled tree**  $t : \{0, 1\}^* \rightarrow \Omega$ , a **run-tree** of  $M$  is a  **$Q$ -labeled tree**  $s : \{0, 1\}^* \rightarrow Q$  such that
  - $s(\epsilon) \in Q_0$ , where  $\epsilon$  is empty and represents the root of the binary tree.
  - for any  $u \in \{0, 1\}^*$ ,  $(s(u), t(u), s(u0), s(u1)) \in \delta$ .
- To simplify the discussion, assume that for any input, a run-tree can be constructed. (Such an automaton is said to be **complete**).

## Recap



- For a  $Q$ -labeled tree  $s$  and an infinite path  $\alpha : \mathbb{N} \rightarrow \{0, 1\}^*$ ,  $s(\alpha)$  denotes the  $\omega$ -sequence of states (labels) on a path  $\alpha$  in  $s$ .  $\text{Inf}(s(\alpha))$  denotes the set of states which appears infinitely often on  $s(\alpha)$ .
- An input tree  $t$  is accepted by a tree automaton  $M$  ( $t \in L(M)$ ) iff there is a run-tree  $s$  in which all its infinite paths  $s(\alpha)$  satisfy the following condition.
  - For a **Büchi tree automaton** (BTA)  $M$ , the acceptance condition  $\text{Acc}$  is  $F(\subseteq Q) : \text{Inf}(s(\alpha)) \cap F \neq \emptyset$ .
  - For a **Muller tree automaton** (MTA)  $M$ ,  $\text{Acc}$  is  $\mathcal{F}(\subseteq \mathcal{P}(Q)) : \text{Inf}(s(\alpha)) \in \mathcal{F}$ .
  - For a **Rabin tree automata**(RTA)  $M$ ,  $\text{Acc}$  is  $\mathcal{F} = \{(G_i, R_i) \mid 1 \leq i \leq k\}$ , where  $G_i, R_i \subseteq Q$ : there exists  $i$  satisfying  $\text{Inf}(s(\alpha)) \cap G_i \neq \emptyset$  and  $\text{Inf}(s(\alpha)) \cap R_i = \emptyset$ .
  - For a **parity tree automaton** (PTA)  $M$ ,  $\text{Acc}$  is a priority function  $\pi : Q \rightarrow \{0, 1, \dots, k\} : \min\{\pi(q) : q \in \text{Inf}(s(\alpha))\}$  is even.
- Even with nondeterminism, BTA has less expressive power than the other three.  $\text{PTA} \rightarrow \text{RTA} \rightarrow \text{NMA}$  is easy, and  $\text{NMA} \rightarrow \text{PTA}$  was shown in the last lecture.

## Parity condition of PTA

## Theorem 6.20

PTA and MTA accept the same languages.

**Proof.** A parity condition can be easily expressed as a Muller condition:  $F \in \mathcal{F}$  iff  $F$  is a set of states whose smallest priority is even.

Conversely, given an MTA  $M = (Q, \Omega, \delta, Q_0, \mathcal{F})$ , we want to construct a PTA  $M' = (Q', \Omega, \delta', Q'_0, \pi)$  which accepts the same language.

- Let  $Q'$  be the set of permutations of  $Q \cup \{\natural\}$  (where  $\natural \notin Q$ ). An element of  $Q'$  denotes a **Last Appearing Record** of the states so that the rightmost  $q$  corresponds to the current state of  $M$ , and  $\natural$  represents the place where such  $q$  appeared just before now. If  $\delta(p, a, r_1, r_2)$  in  $M$  and  $q_1 \dots q_m \natural q_{m+1} \dots q_n \in Q'$  and  $q_n = p, q_i = r_1, q_j = r_2$ ,

$$\delta'(q_1 \dots q_m \natural q_{m+1} \dots q_n, a, q_1 \dots q_{i-1} \natural q_{i+1} \dots q_n q_i, q_1 \dots q_{j-1} \natural q_{j+1} \dots q_n q_j).$$

- A priority function  $\pi : Q' \rightarrow \{0, 1, \dots, 2|Q| + 1\}$  is defined as follows: For  $u \natural v \in Q'$ ,

$$\pi(u \natural v) = 2|u| \text{ if } \{q \in Q : v \text{ contains } q\} \in \mathcal{F}; \quad = 2|u| + 1 \text{ otherwise.}$$

- $Q'_0$  can be  $Q'$ , but a more efficient choice is the set of sequences in  $Q'$  with the rightmost belonging to  $Q_0$ .

- We compare the run-trees of MTA  $M$  and PTA  $M'$  for the same input tree.
- A state  $q$  that appears finitely (infinitely) many times in a path of the run-tree of  $M$  also occurs finitely (infinitely) many times to the right of  $\natural$  in the corresponding path of the run-tree of  $M'$ .
- Therefore, from a certain time onwards, the states that appear finitely are fixed in a sequence  $u$  on the left side of  $\natural$ , and the states that appears infinitely and  $\natural$  are permuted repeatedly. We fix such a sequence  $u$  and let  $V$  be the set of states not in  $u$ .
- If  $\natural$  comes to the leftmost in the sequence, that is, if it comes immediately after  $u$ , it has the lowest priority. Such cases always occur infinitely. So,  $V$  is the set of states appearing infinitely many times. Hence, if a path satisfies the acceptance of  $M$ , i.e.,  $V \in \mathcal{F}$ , the lowest priority of states of  $M'$  appearing infinitely many time is even, and so it also satisfies the acceptance condition for  $M'$ .
- Conversely, consider a path satisfying the acceptance condition of  $M'$ . Since the states appearing infinitely with the lowest priority is  $u\natural v$  for a sequence  $v$  from  $V$ , the path also satisfies the acceptance condition of  $M$  because the lowest priority must be even.
- Therefore, the accepted tree languages of  $M$  and  $M'$  are the same. □

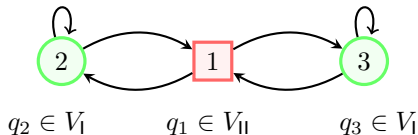
## Parity games

A parity game  $G = (V_I, V_{II}, E, \pi)$  is a game on a directed graph  $(V_I \cup V_{II}, E)$  with a priority function  $\pi : V_I \cup V_{II} \rightarrow \{0, 1, \dots, k\}$ :

- The set of vertices is partitioned into  $V_I$  and  $V_{II}$  ( $V_I \cap V_{II} = \emptyset$ ).
- Two players, player I and II, move a token along the edges of the graph, which results in a path  $\rho = v_0 v_1 \dots$ , called a **play**.
- At a vertex  $v \in V_I$  ( $V_{II}$ ), it is player I (II)'s turn to choose some  $v'$  such that  $(v, v') \in E$ . Note that the choice of  $v'$  may depend on the past moves.
- A strategy for player I is a mapping  $\sigma : (V_I \cup V_{II})^{<\omega} V_I \rightarrow V_I \cup V_{II}$ .  
A strategy for player II is a mapping  $\tau : (V_I \cup V_{II})^{<\omega} V_{II} \rightarrow V_I \cup V_{II}$ .
- The winner of a finite play is the player whose opponent is unable to move.
- Parity winning condition: Player I wins with an infinite play if the smallest priority that occurs infinitely often in the play is even. II wins otherwise
- $\sigma$  is a **winning strategy for player I** if whenever he follows  $\sigma$  the resulting play satisfies the parity condition.

## Example

Consider the following parity game  $G = (V_I, V_{II}, E, \pi)$ , where  $V_I = \{q_2, q_3\}$  and  $V_{II} = \{q_1\}$ ,  $\pi(q_i) = i$  for  $i = 1, 2, 3$ .



Assume the game starts from  $q_1$ , player II has a winning strategy.

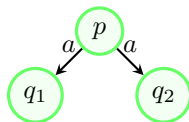
- A game  $G$  is said to be **determined** if one of the two players has a winning strategy.
- A game  $G$  is said to be **positionally determined** if one of the two players has a memoryless winning strategy.
- A **memoryless** strategy for player I is a mapping  $\sigma : V_I \rightarrow V_I \cup V_{II}$ .  
A **memoryless** strategy for player II is a mapping  $\tau : V_{II} \rightarrow V_I \cup V_{II}$ .
- As we'll show later, parity games are positionally determined. ◻ ▶ ◀ ◻ ▶ ◀ ≡ ▶ ◀ ≡ ▶ ≡ ▶ ≡ ▶ ≡ ▶



## Express a PTA as an infinite game

- Given a PTA  $M = (Q, \Omega, \delta, Q_0, \pi)$  and an input tree  $t$ , we construct an infinite game  $G(M, t)$  in which two players alternately move as follows:

- (1) Player I (Automaton) chooses a next pair of states  $(q_1, q_2)$  from  $\delta(p, a)$ .
- (2) Player II (Path Finder) chooses either 0 or 1 for the next direction.



- The **goal of the Path Finder** is to find a path  $\alpha \subseteq \{0, 1\}^*$  in the run-tree  $s$  that does not satisfy the acceptance condition, whereas the **goal of the Automaton** is to find the  $Q$  labels of the run-tree so that the label sequence satisfies the acceptance conditions.
- Player I (automaton) wins in  $G(M, t)$  if the label string  $s(\alpha)$  produced by the two players satisfies the acceptance condition of  $M$ .
- Thus “ $M$  accepts  $t \Leftrightarrow$  The automaton has a winning strategy in  $G(M, t)$ .”
- Assume the determinacy of this game (either player has a winning strategy),  
“ $M$  does not accept  $t \Leftrightarrow$  The path finder has a winning strategy in  $G(M, t)$ .”
- For the moment, we also assume the following (which we will prove in next week).  
“The parity game is positionally determined.”

Now we present the main lemma.

## Lemma 6.21

For any PTA  $M$ , there is a PTA  $M'$  that accepts the complement of  $L(M)$ .

### Proof.

- Let  $M = (Q, \Omega, \delta, Q_0, \pi)$  be a PTA and  $L^c$  the complement of  $L(M)$ . First, we will define a parity game  $G(M, t)$  such that  
 “an input tree  $t$  belongs to  $L^c \Leftrightarrow$  player II has a winning strategy.”
- $G(M, t) = (V_I, V_{II}, E, \pi)$  is defined as follows:  
 $V_I = \{0, 1\}^* \times Q$ ,  $V_{II} = \{(d, (q, q_0, q_1)) \in \{0, 1\}^* \times Q^3 : \delta(q, t(d), q_0, q_1)\}$ ,  
 $E = \{(d, (q, q_0, q_1)), (d \hat{\ } i, q_i) \in V_{II} \times V_I : i = 0, 1\} \cup \{((d, q), (d, (q, q_0, q_1))) \in V_I \times V_{II}\}$ .
- The game starts with I by choosing an element from  $\{\epsilon\} \times Q_0$ .
- The priority function of the games follows  $\pi$  of PTA  $M$ , i.e., the priority for  $(d, (q, q_0, q_1)) \in V_{II}$  and  $(d, q) \in V_I$  are both  $\pi(q)$ . Then, the same  $\pi(q)$  always appears twice consecutively, but it does not matter with the parity condition. Player I wins when the smallest priority appearing infinitely often is even.

- Let  $S_{\text{II}}$  be the set of total functions from  $Q^3$  to  $\{0, 1\}$ . Then, II's memoryless strategy can be viewed as  $\sigma : \{0, 1\}^* \rightarrow S_{\text{II}}$ . Hence, it can also be viewed as a  $S_{\text{II}}$ -labelled tree.
- So, given an input tree  $t$  and a memoryless strategy  $\sigma$  for II (not necessarily a winning strategy), we have a  $\Omega \times S_{\text{II}}$ -labelled tree of  $(a_0, s_0)(a_1, s_1)(a_2, s_2) \cdots (a_n, s_n)$  such that  $a_i = t(d_0 d_1 \cdots d_{i-1})$ ,  $s_i = \sigma(d_0 d_1 \cdots d_{i-1})$  ( $d_i \in \{0, 1\}$ ,  $0 \leq i \leq n$ ).
- Moreover, we treat an infinite path  $(a_0, s_0)(a_1, s_1)(a_2, s_2) \cdots$  through this tree as an  $\omega$ -word  $\alpha = (a_0, s_0, d_0)(a_1, s_1, d_1)(a_2, s_2, d_2) \cdots$  on  $\Omega' = \Omega \times S_{\text{II}} \times \{0, 1\}$ .  
Let  $L(t, \sigma)$  denote the set of all such words.
- We can define an NPA  $A$  which accepts an  $\omega$ -word  $\alpha = (a_0, s_0, d_0)(a_1, s_1, d_1) \cdots$  iff a sequence  $q_0, q_1, q_2 \cdots$  can be chosen consistently with  $\alpha$  to satisfy the parity condition.
- Now, we set  $A = (Q, \Omega', \delta', Q_0, \pi)$ , where  $Q, Q_0, \pi$  are the same as the PTA  $M$ , and  $\Omega' = \Omega \times S_{\text{II}} \times \{0, 1\}$ , and

$$\delta' = \{(q, (a, s, i), q_i) : \text{there exists } (q, a, q_0, q_1) \in \delta \text{ s.t. } s(q, q_0, q_1) = i\}.$$

Note that this definition does not depend on II's strategy  $\sigma$ .

## Claim 1

II's memoryless strategy  $\sigma$  is the winning strategy  $\Leftrightarrow L(t, \sigma) \cap L(A) = \emptyset$ .

( $\Rightarrow$ ) By way of contradiction, let  $\alpha \in L(t, \sigma) \cap L(A)$ .

- Then there exists a run  $q_0 q_1 q_2 \cdots$  of  $A$  on input  $\alpha$  satisfying the parity condition.
- On the other hand, for II's strategy  $\sigma$ , if player I chooses  $(q, a, q_0, q_1) \in \delta$  following  $\delta'$ , then they produce a play  $q_0 q_1 q_2 \cdots$  in which I wins. So,  $\sigma$  is not a winning strategy.

( $\Leftarrow$ ) By way of contradiction, suppose strategy  $\sigma$  is not a winning strategy for II.

- If player I chooses  $(q, a, q_0, q_1) \in \delta$  appropriately, there exists  $\alpha = (a_0, s_0, d_0)(a_1, s_1, d_1) \cdots$  such that its corresponding  $q_0, q_1, q_2 \cdots$  satisfies the parity condition.
- Thus  $\alpha \in L(t, \sigma) \cap L(A)$ .

Now, since  $L(A)$  is an  $\omega$ -regular language, there exists a DPA  $A' = (P, \Omega', \eta, q_0, \pi')$  that accepts the complement of  $L(A)$  on  $\Omega'$ .

- Then we construct a desired PTA  $M'$  from a DPA  $A'$ . That is,  $M' = (P, \Omega, \eta', P_0, \pi')$ ,

$$\eta' = \{(p, a, p_0, p_1) : \exists s \in S_{\text{II}} ((p, (a, s, 0), p_0) \in \eta \wedge (p, (a, s, 1), p_1) \in \eta)\}.$$

Claim 2

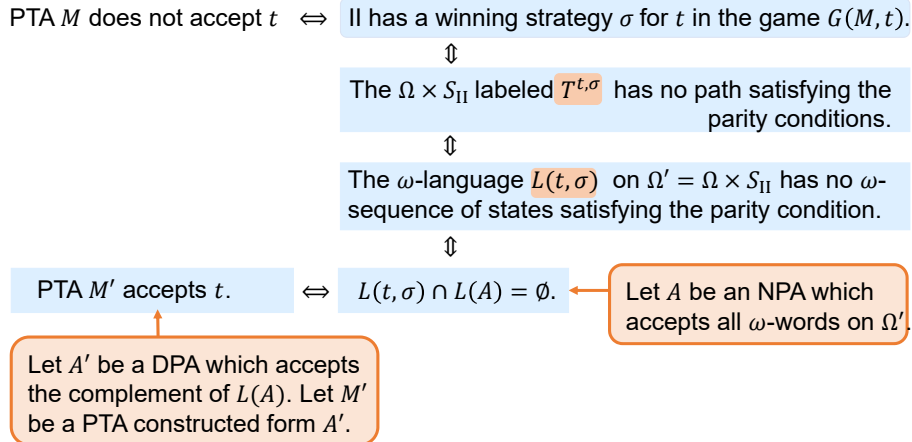
$$t \in L(M') \Leftrightarrow t \notin L(M).$$

( $\Rightarrow$ ) Suppose  $t \in L(M')$ , and fix an accepting run-tree  $r$ .

- For each node  $d \in \{0, 1\}^*$  in  $r$ , there exists  $s_d \in S_{\text{II}}$  satisfying  $\eta'$ .
- Then we merge them to define a memoryless strategy  $\sigma : \{0, 1\}^* \rightarrow S_{\text{II}}$ .
- Next, consider a run of DPA  $A'$  for an  $\omega$ -word  $\alpha$  in  $L(t, \sigma)$ . It is the sequence of labels of the tree  $r$  for the  $\{0, 1\}^\omega$  components of  $\alpha$  and satisfies the parity condition. So  $\alpha \in L(A')$ , which means  $\alpha \notin L(A)$ .
- Thus,  $L(t, \sigma) \cap L(A) = \emptyset$ . By Claim 1,  $\sigma$  is a memoryless winning strategy for II in  $G(M, t)$ . Therefore,  $t \notin L(M)$ .

- ( $\Leftarrow$ ) Suppose  $t \notin L(M)$ .
- Then player II has a memoryless winning strategy  $\sigma$  in  $G(M, t)$ , which can be viewed as a  $S_{II}$ -labeled tree. From claim 1,  $L(t, \sigma) \cap L(A) = \emptyset$ , so  $L(t, \sigma) \subset L(A')$ .
- A  $P$ -labeled sequence of DPA  $A'$  for a finite subsequence of  $\omega$ -word  $\alpha$  in  $L(t, \sigma)$  is uniquely determined. Based on them, there exists a  $P$ -labeled tree  $r$  which is a run-tree of  $M'$  for  $t$ .
- Since each  $P$ -labeled path of the tree  $r$  satisfies the parity condition,  $r$  satisfies the acceptance condition of  $M'$  and so  $M'$  accepts the input tree  $t$ . □

The outline of the proof is shown in the following diagram.



Using a parity game similar to  $G(M, t)$  above, it is easy to show the following.

## Lemma 6.22 (PTA emptiness problem)

It is decidable whether the accepted language of PTA is empty or not.

**Proof.** Given PTA  $M = (Q, \Omega, \delta, Q_0, \pi)$ , consider the following parity game  $G(M) = (V_1, V_2, E, Q_0, \pi')$ .

- $V_1 = Q, \quad V_2 = \delta,$
- $E = \{(q, (q, a, q_0, q_1)) \in V_1 \times V_2\} \cup \{((q, a, q_0, q_1), q_i) \in V_2 \times V_1 : i = 0, 1\},$
- $\pi'(q) = \pi(q), \quad \pi'((q, a, q_0, q_1)) = \pi(q).$

This is like removing the position information  $d \in \{0, 1\}^*$  from the above  $G(M, t)$ .  
Therefore,

Player I has a winning strategy in  $G(M)$  starting from a state in  $Q_0 \Leftrightarrow L(M) \neq \emptyset$

And if player I has a winning strategy in  $G(M)$ , he has a memoryless winning strategy.  
Since  $V_1, V_2$  are finite sets, it is decidable in finite steps that player I has a winning strategy.



## S2S and MTA

- Now we will show the equivalence of S2S and MTA.
- First, to translate an S2S formula  $\varphi(\vec{x}, \vec{X})$  into a tree language, we need something like the characteristic sequence we defined to translate S1S.
- For simplicity, we replace the first-order variable  $x$  with second-order variable  $X$  representing the singleton set, and consider the translation of the formula  $\varphi(\vec{X})$  with no free occurrences of first-order variables.
- Let  $\vec{T} = (T_1, \dots, T_n)$  be an  $n$ -tuple of subsets of  $\{0, 1\}^*$ . Letting  $\Omega = \{0, 1\}^n$ , we express  $\vec{T}$  by an  $\Omega$ -labeled tree  $t : \{0, 1\}^* \rightarrow \{0, 1\}^n$  such that for each  $i = 1, \dots, n$ ,

$$T_i = \{d \in \{0, 1\}^* : i\text{th element of } t(d) \text{ is } 1\}$$

Then, such a  $t$  is called the **characteristic representation tree** (representation tree, in short) of  $\vec{T}$ .

## Lemma 6.23

Given an S2S formula  $\varphi(\vec{X})$ , there exists an MTA  $M_\varphi$  on  $\Omega = \{0, 1\}^n$  such that,

$$L(M_\varphi) = \{ \text{The representation tree of } \vec{T} : \varphi(\vec{T}) \text{ holds} \}.$$

**Proof.** The atomic formula of S2S has a form

$$S_{b_1} S_{b_2} \dots S_{b_k} x \in X \text{ (where } b_i = 0, 1).$$

Then  $(d, T)$  satisfies the above relation iff the word  $db_k \dots b_2 b_1$  belongs to  $T$ . So, it is easy to construct a PTA  $M$  that accepts the set of the representation trees of such  $(d, T)$ 's. Furthermore, since the class of languages accepted by MTA's is closed under Boolean operations and projections, any S2S formula has an equivalent MTA.  $\square$

# Thank you for your attention!