

# 粒子理论专题 动力学对称性自发破缺

王青

清华大学

2007年10月10日-2007年11月25日

圈图展开与有效势

Coleman-Weinberg理论

Gross-Neveu模型

局域复合算符的有效势

**圈图展开** Y.Nambu, Phys. Lett. B26, 626 (1968) 普通微扰论破坏规范对称性:  $\mathcal{L} = -\frac{1}{4} G_{\mu\nu}^a G^{a\mu\nu}$

$$\mathcal{L}_0 = -\frac{1}{4} (\partial_\mu G_\nu^a - \partial_\nu G_\mu^a)^2 \quad \mathcal{L}_{\text{int}} = -g C_{abc} (\partial_\mu G_\nu^a) G_\mu^b G_\nu^c - \frac{1}{4} g^2 C_{abc} C_{ade} G_\mu^b G_\nu^c G_\mu^d G_\nu^e$$

在微扰论中, 规范对称性的破坏与否只能准确到微扰论计算所达到的精度!  
无法准确地判断自发破缺的发生与否

构造不破坏对称性的展开方法: 按 $\hbar$ 幂次展开 = 半经典展开

当量子涨落效应比较小时:  $Z[J] = e^{\frac{i}{\hbar} W[J]} = \int \mathcal{D}\phi e^{\frac{i}{\hbar} \int d^4x (\mathcal{L} + \hbar J\phi)}$  可按 $\hbar$ 的正幂次进行展开

$$\begin{aligned} \phi = \sqrt{\hbar}\phi' \quad Z[J] &= e^{\frac{i}{\hbar} W[J]} = \int \mathcal{D}\phi' e^{i \int d^4x [\mathcal{L}_0(\phi') \text{ 二次项} + \frac{1}{\hbar} \mathcal{L}_{\text{int}}(\sqrt{\hbar}\phi') + \sqrt{\hbar} J\phi']} \\ &= e^{i \int d^4x \frac{1}{\hbar} \mathcal{L}_{\text{int}}(\frac{1}{i} \frac{\delta}{\delta J})} e^{\frac{i}{2} \iint d^4x d^4y \hbar J(x) \Delta'(x-y) J(y)} \quad \Delta'(x-y) = \langle 0 | T \phi'(x) \phi'(y) | 0 \rangle \end{aligned}$$

分析以 $\phi'$ 构造的费曼图,  $E$ 条外线,  $I$ 条内线,  $V$ 个顶角

$$\text{费曼图的}\hbar\text{幂次: } \hbar^{\frac{E}{2} + I - V} \stackrel{L=I-(V-1)}{=} \hbar^{\frac{E}{2} + L - 1}$$

给定外线的费曼图 按圈的数目展开等价于按 $\hbar$ 的幂次展开! 量子涨落是以圈的数目衡量的!

有些理论 圈展开=微扰展开:  $\lambda\phi^4$   $L \stackrel{4V=E+2I}{=} V + 1 - E/2$  有多种顶角(真空期望值)时除外

## 有效势

$$Z[J] = e^{iW[J]} = \int \mathcal{D}\phi e^{i \int d^4x (\mathcal{L} + J\phi)} \quad \text{定义经典场: } \hat{\phi}(x) \equiv \frac{\delta W[J]}{\delta J(x)} = -i \frac{1}{Z[J]} \frac{\delta Z[J]}{\delta J(x)}$$

$$\text{有效作用量: } \Gamma[\hat{\phi}] \equiv W[J] - \int d^4x J(x) \hat{\phi}(x)$$

$$\frac{\delta \Gamma[\hat{\phi}]}{\delta \hat{\phi}(x)} = \int d^4y \frac{\delta W}{\delta J(y)} \frac{\delta J(y)}{\delta \hat{\phi}(x)} - \int d^4y \left[ \frac{\delta J(y)}{\delta \hat{\phi}(x)} \hat{\phi}(y) + J(y) \delta(x-y) \right] = -J(x)$$

对比经典的含外源的作用量所满足的场方程:

$$S_J(\phi) \equiv \int d^4x [\mathcal{L}(\phi) + J\phi] \quad \text{场方程: } \frac{\delta S_J(\phi)}{\delta \phi(x)} = 0 \Rightarrow \frac{\delta \int d^4y \mathcal{L}[\phi]}{\delta \phi(x)} = -J(x)$$

$$\Gamma^{(n)}(x_1, \dots, x_n) \equiv \frac{\delta^n \Gamma}{\delta \hat{\phi}(x_1) \dots \delta \hat{\phi}(x_n)} \quad \Gamma^{(n)}(x_1, \dots, x_n) \Big|_{J=0} = \mathbf{n} \text{点一粒子不可约顶角}$$

$$\hat{\phi}(x) \stackrel{J=0}{=} v \quad \Gamma[\hat{\phi}] = \sum_n \int d^4x_1 \dots d^4x_n \frac{1}{n!} \Gamma^{(n)}(x_1, \dots, x_n) [\hat{\phi}(x_1) - v] \dots [\hat{\phi}(x_n) - v]$$

一粒子不可约顶角生成泛函

两线顶角:

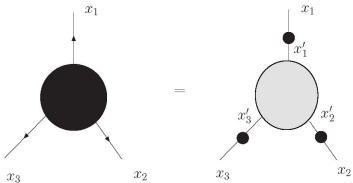
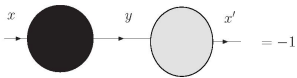
$$\delta(x-x') = \frac{\delta\hat{\phi}(x)}{\delta\hat{\phi}(x')} = \int d^4y \frac{\delta\hat{\phi}(x)}{\delta J(y)} \frac{\delta J(y)}{\delta\hat{\phi}(x')} = - \int d^4y \frac{\delta^2 W[J]}{\delta J(x)\delta J(y)} \frac{\delta^2 \Gamma[\hat{\phi}]}{\delta\hat{\phi}(y)\delta\hat{\phi}(x')}$$

三线顶角:

$$0 = \frac{\delta}{\delta J(x_3)} \int d^4x_2 \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x_2)} \frac{\delta \Gamma[\hat{\phi}]}{\delta\hat{\phi}(x_2)\delta\hat{\phi}(x')}$$

$$= \int d^4x_2 \left[ \frac{\delta^3 W[J]}{\delta J(x_1)\delta J(x_2)\delta J(x_3)} \frac{\delta^2 \Gamma[\hat{\phi}]}{\delta\hat{\phi}(x_2)\delta\hat{\phi}(x')} + \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x_2)} \int d^4y \frac{\delta^3 \Gamma[\hat{\phi}]}{\delta\hat{\phi}(y)\delta\hat{\phi}(x_2)\delta\hat{\phi}(x')} \frac{\delta\hat{\phi}(y)}{\delta J(x_3)} \right]$$

$$\frac{\delta^3 W[J]}{\delta J(x_1)\delta J(x_2)\delta J(x_3)} = \int d^4x'_1 d^4x'_2 d^4x'_3 \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x'_1)} \frac{\delta^2 W[J]}{\delta J(x_2)\delta J(x'_2)} \frac{\delta^2 W[J]}{\delta J(x_3)\delta J(x'_3)} \frac{\delta^3 \Gamma[\hat{\phi}]}{\delta\hat{\phi}(x'_1)\delta\hat{\phi}(x'_2)\delta\hat{\phi}(x'_3)}$$



四线顶角:  $\frac{\delta^4 W[J]}{\delta J(x_1)\delta J(x_2)\delta J(x_3)\delta J(x_4)}$

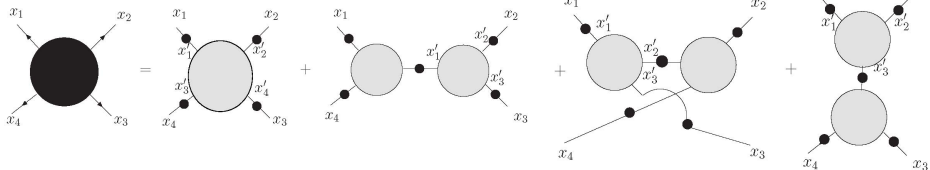
$$= \frac{\delta}{\delta J(x_4)} \left[ \int d^4 x'_1 d^4 x'_2 d^4 x'_3 \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x'_1)} \frac{\delta^2 W[J]}{\delta J(x_2)\delta J(x'_2)} \frac{\delta^2 W[J]}{\delta J(x_3)\delta J(x'_3)} \frac{\delta^3 \Gamma[\hat{\phi}]}{\delta \hat{\phi}(x'_1)\delta \hat{\phi}(x'_2)\delta \hat{\phi}(x'_3)} \right]$$

$$= \int d^4 x'_1 d^4 x'_2 d^4 x'_3 d^4 x'_4 \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x'_1)} \frac{\delta^2 W[J]}{\delta J(x_2)\delta J(x'_2)} \frac{\delta^2 W[J]}{\delta J(x_3)\delta J(x'_3)} \frac{\delta^2 W[J]}{\delta J(x_4)\delta J(x'_4)}$$

$$\times \frac{\delta^4 \Gamma[\hat{\phi}]}{\delta \hat{\phi}(x'_1)\delta \hat{\phi}(x'_2)\delta \hat{\phi}(x'_3)\delta \hat{\phi}(x'_4)} + \int d^4 x'_1 d^4 x'_2 d^4 x'_3 \frac{\delta^3 \Gamma[\hat{\phi}]}{\delta \hat{\phi}(x'_1)\delta \hat{\phi}(x'_2)\delta \hat{\phi}(x'_3)}$$

$$\times \left[ \frac{\delta^3 W[J]}{\delta J(x_1)\delta J(x'_1)\delta J(x_4)} \frac{\delta^2 W[J]}{\delta J(x_2)\delta J(x'_2)} \frac{\delta^2 W[J]}{\delta J(x_3)\delta J(x'_3)} + \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x'_1)} \frac{\delta^3 W[J]}{\delta J(x_2)\delta J(x'_2)\delta J(x_4)} \frac{\delta^2 W[J]}{\delta J(x_3)\delta J(x'_3)} \right]$$

$$+ \frac{\delta^2 W[J]}{\delta J(x_1)\delta J(x'_1)} \frac{\delta^2 W[J]}{\delta J(x_2)\delta J(x'_2)} \frac{\delta^3 W[J]}{\delta J(x_3)\delta J(x'_3)\delta J(x_4)} \Big]$$



真空态的平移不变性:  $\hat{\phi}(x) \stackrel{J=0}{=} \hat{\phi}(x+a)$  真空期望值是与坐标无关的常数!

研究具有平移不变性的  $\hat{\phi}(x) = \hat{\phi}$   $\Gamma^{(n)}(x_1, \dots, x_n) \equiv \frac{\delta^n \Gamma}{\delta \hat{\phi}(x_1) \cdots \delta \hat{\phi}(x_n)}$  只依赖  $n-1$  个坐标

$$\Gamma[\hat{\phi}] = \sum_n \int d^4x_1 \cdots d^4x_n \frac{1}{n!} \Gamma^{(n)}(x_1, \dots, x_n) [\hat{\phi}(x_1) - v] \cdots [\hat{\phi}(x_n) - v] \text{ 对平移不变 } \hat{\phi} \text{ 含一整体 } \int d^4x \text{ 因子}$$

$$\Gamma[\hat{\phi}] = -V_{\text{eff}}(\hat{\phi}) \int d^4x \text{ 包含所有有效作用量中不含场的微商的相互作用项} \stackrel{\frac{\delta \Gamma}{\delta \hat{\phi}} \Big|_{J=0} = 0}{\implies} \frac{\partial V_{\text{eff}}[\hat{\phi}]}{\partial \hat{\phi}} \Big|_{\hat{\phi}=v} = 0$$

$\phi(x) = \hat{\phi} + \tilde{\phi}(x)$ ,  $\mathcal{D}\phi = \mathcal{D}\tilde{\phi}$ , 若略去量子涨落  $\tilde{\phi}(x)$  圈图的贡献

$$Z[J] = e^{iW[J]} = e^{i \int d^4x [-V(\hat{\phi}) + J(x)\hat{\phi}]} \Rightarrow W[J] = \int d^4x [-V(\hat{\phi}) + J(x)\hat{\phi}]$$

$$\Gamma[\hat{\phi}] = W[J] - \int d^4x J(x)\hat{\phi} = -V(\hat{\phi}) \int d^4x \stackrel{\text{略去 } \tilde{\phi}(x)}{\implies} V_{\text{eff}}(\hat{\phi}) = V(\hat{\phi}) \text{ } \tilde{\phi}(x) \text{ 的修正需要计算圈图!}$$

标准模型对真空的非微扰估计主要就是在此水平上进行的! 另加小的圈图修正

$$V_{\text{eff}}(\hat{\phi}) = -\sum_n \int d^4x_2 \cdots d^4x_n \frac{1}{n!} \Gamma^{(n)}(0, x_2-x_1, \dots, x_n-x_1) (\hat{\phi}-v)^n = -\sum_n \frac{1}{n!} \Gamma^{(n)}(p_1=0, \dots, p_n=0) (\hat{\phi}-v)^n$$

## 有效势的泛函计算

▶ R.Jackiw, Phys.Rev.D9,1686(1974)

▶ J.Iliopoulos, C.Itzykson, and A.Martin, Rev. Mod. Phys.47, 165(1975)

$$S = \int d^4x \mathcal{L} \quad S_J = \int d^4x (\mathcal{L} + J\phi) \quad \text{经典解 } \phi_{\text{cl}} \text{ 满足: } \frac{\delta S_J[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}} = 0 \Rightarrow \frac{\delta S[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}(x)} = -J(x)$$

$$\phi = \phi_{\text{cl}} + \tilde{\phi} \quad S_J(\phi_{\text{cl}} + \tilde{\phi}) = S_J(\phi_{\text{cl}}) + \frac{1}{2} \int d^4x d^4y \tilde{\phi}(x) \frac{\delta S[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}(x) \delta \phi_{\text{cl}}(y)} \tilde{\phi}(y) + I_{\text{int}}[\phi_{\text{cl}}, \tilde{\phi}]$$

$$J(x)\tilde{\phi}(x) + \frac{\delta S(\phi_{\text{cl}})}{\delta \phi_{\text{cl}}(x)} \tilde{\phi}(x) = 0 \quad i\mathcal{D}^{-1}(\phi_{\text{cl}}; x, y) \equiv \frac{\delta S[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}(x) \delta \phi_{\text{cl}}(y)}$$

$$S_J(\phi_{\text{cl}} + \tilde{\phi}) = S_J(\phi_{\text{cl}}) + \frac{1}{2} \int d^4x d^4y \tilde{\phi}(x) i\mathcal{D}^{-1}(\phi_{\text{cl}}; x, y) \tilde{\phi}(y) + I_{\text{int}}[\phi_{\text{cl}}, \tilde{\phi}]$$

$$\begin{aligned} Z[J] &= e^{iW[J]} = \int \mathcal{D}\phi e^{iS_J[\phi_{\text{cl}} + \tilde{\phi}]} = e^{iS_J(\phi_{\text{cl}})} \int \mathcal{D}\phi e^{i\{\frac{1}{2} \int d^4x d^4y \tilde{\phi}(x) i\mathcal{D}^{-1}(\phi_{\text{cl}}; x, y) \tilde{\phi}(y) + I_{\text{int}}[\phi_{\text{cl}}, \tilde{\phi}]\}} \\ &= e^{iS_J(\phi_{\text{cl}})} \int \mathcal{D}\phi e^{i\{\frac{1}{2} \int d^4x d^4y \tilde{\phi}(x) i\mathcal{D}^{-1}(\phi_{\text{cl}}; x, y) \tilde{\phi}(y)\}} Z_2[J] = e^{iS_J(\phi_{\text{cl}}) - \frac{1}{2} \text{Tr} \ln \mathcal{D}^{-1}(\phi_{\text{cl}}) + iW_2[J]} \end{aligned}$$

 $O(\hbar^0)$  $O(\hbar^1)$  $O(\hbar^2)$ 

$$Z_2[J] = e^{iW_2[J]} = \frac{e^{i\{\frac{1}{2} \int d^4x d^4y \tilde{\phi}(x) i\mathcal{D}^{-1}(\phi_{\text{cl}}; x, y) \tilde{\phi}(y) + I_{\text{int}}[\phi_{\text{cl}}, \tilde{\phi}]\}}}{e^{i\{\frac{1}{2} \int d^4x d^4y \tilde{\phi}(x) i\mathcal{D}^{-1}(\phi_{\text{cl}}; x, y) \tilde{\phi}(y)\}}}$$

$$\text{Det}^{-\frac{1}{2}} i\mathcal{D}^{-1}(\phi_{\text{cl}}) = e^{-\frac{1}{2} \text{Tr} \ln i\mathcal{D}^{-1}(\phi_{\text{cl}})}$$



$$W[J] = W_0[J] + W_1[J] + W_2[J] \quad W_0[J] = S_J(\phi_{\text{cl}}) = S(\phi_{\text{cl}}) + \int d^4x J\phi_{\text{cl}} \quad W_1[J] = \frac{i}{2} \text{Tr} \ln i\mathcal{D}^{-1}(\phi_{\text{cl}})$$

$$\hat{\phi} = \frac{\delta W}{\delta J} \quad \frac{\delta W_0}{\delta J(x)} = \int d^4y \frac{\delta S[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}(y)} \frac{\delta \phi_{\text{cl}}(y)}{\delta J(x)} + \int d^4y \left[ \frac{\delta \phi_{\text{cl}}(y)}{\delta J(x)} J(y) + \phi_{\text{cl}}(y) \delta(x-y) \right] = \phi_{\text{cl}}(x)$$

$$\hat{\phi} = \phi_{\text{cl}} + \phi_1 \quad \phi_1 = \frac{\delta W_L}{\delta J(x)} \quad W_L = W_1 + W_2$$

$$\Gamma[\hat{\phi}] = W[J] - \int d^4x J\hat{\phi} = S[\phi_{\text{cl}}] + \int d^4x J[\phi_{\text{cl}}](\phi_{\text{cl}} - \hat{\phi}) + W_L[\phi_{\text{cl}}] = S[\hat{\phi} - \phi_1] + \int d^4x J\phi_1 + W_L[\hat{\phi} - \phi_1]$$

$$= S[\hat{\phi}] - \int d^4x \frac{\delta S[\hat{\phi}]}{\delta \hat{\phi}(x)} \phi_1(x) + \frac{1}{2} \int d^4x d^4y \phi_1(x) \frac{\delta S[\hat{\phi}]}{\delta \hat{\phi}(x) \delta \hat{\phi}(y)} \phi_1(y) - \int d^4x J[\phi_{\text{cl}}] \phi_1$$

$$+ W_L[\hat{\phi}] - \int d^4x \frac{\delta W_L[\hat{\phi}]}{\delta \hat{\phi}(x)} \phi_1(x) + O(\hbar^3)$$

$$\int d^4x \left[ \frac{\delta S[\hat{\phi}]}{\delta \hat{\phi}(x)} + J[\phi_{\text{cl}}] \right] \phi_1(x) = \int d^4x \left[ \frac{\delta S[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}(x)} + \int d^4y \frac{\delta^2 S[\phi_{\text{cl}}]}{\delta \phi_{\text{cl}}(x) \delta \phi_{\text{cl}}(y)} \phi_1(y) + J[\phi_{\text{cl}}] \right] \phi_1(x)$$


$$\Gamma[\hat{\phi}] = S[\hat{\phi}] - \frac{1}{2} \int d^4x d^4y \phi_1(x) \frac{\delta S[\hat{\phi}]}{\delta \hat{\phi}(x) \delta \hat{\phi}(y)} \phi_1(y) + W_L[\hat{\phi}] - \int d^4x \frac{\delta W_L[\hat{\phi}]}{\delta \hat{\phi}(x)} \phi_1(x) + O(\hbar^3)$$

$$= \Gamma_0[\hat{\phi}] + \Gamma_1[\hat{\phi}] + \Gamma_2[\hat{\phi}] + O(\hbar^3)$$

$$\Gamma[\hat{\phi}] = \Gamma_0[\hat{\phi}] + \Gamma_1[\hat{\phi}] + \Gamma_2[\hat{\phi}] + O(\hbar^3) \quad \Gamma_0[\hat{\phi}] = S[\hat{\phi}] \quad \Gamma_1[\hat{\phi}] = W_1[\hat{\phi}] = \frac{i}{2} \text{Tr} \ln iD^{-1}(\hat{\phi})$$

$$\Gamma_2[\hat{\phi}] = -\frac{1}{2} \int d^4x d^4y \phi_1(x) \frac{\delta S[\hat{\phi}]}{\delta \hat{\phi}(x) \delta \hat{\phi}(y)} \phi_1(y) + W_2[\hat{\phi}] - \int d^4x \frac{\delta W_2[\hat{\phi}]}{\delta \hat{\phi}(x)} \phi_1(x)$$

实际例子 以  $D^{-1}(\phi_{cl}; x, y)$  为传播子,  $I_{\text{int}}[\hat{\phi}, \tilde{\phi}]$  为相互作用顶角的所有一粒子不可约两圈图

$$\Gamma[\hat{\phi}] = S[\hat{\phi}] + \frac{i}{2} \text{Tr} \ln iD^{-1}(\hat{\phi}) + \bar{\Gamma}_2 \quad \bar{\Gamma}_2 = \sum_{n=2}^{\infty} \Gamma_n[\hat{\phi}]$$


$\Gamma_n[\hat{\phi}] =$  以  $D(\phi_{cl}; x, y)$  为传播子,  $I_{\text{int}}[\hat{\phi}, \tilde{\phi}]$  为相互作用顶角的所有一粒子不可约  $n$  圈图

$$e^{i\Gamma[\hat{\phi}]} = e^{iW[J] - i \int d^4x J \hat{\phi}} = \int \mathcal{D}\phi e^{iS[\phi] + i \int d^4x J(\phi - \hat{\phi})} = \int \mathcal{D}\tilde{\phi} e^{iS[\hat{\phi} + \tilde{\phi}] + i \int d^4x J \tilde{\phi}}$$

$$\Gamma_1 + \bar{\Gamma}_2 = \Gamma - \Gamma_0 = -i \ln \int \mathcal{D}\tilde{\phi} e^{i\{S[\hat{\phi} + \tilde{\phi}] - S[\hat{\phi}] + J\tilde{\phi}\}} = -i \ln \int \mathcal{D}\tilde{\phi} e^{i \int d^4x [\frac{1}{2} \tilde{\phi} i D^{-1} \tilde{\phi} + \mathcal{L}_{\text{int}}(\hat{\phi}, \tilde{\phi})]}$$

$$\frac{\partial \bar{\Gamma}_2}{\partial D} = -D^{-1} \frac{\partial(\Gamma_1 + \bar{\Gamma}_2)}{\partial D^{-1}} D^{-1} + \frac{i}{2} D^{-1} = \frac{i}{2} D^{-1} \frac{\int \mathcal{D}\tilde{\phi} \tilde{\phi} \tilde{\phi} e^{i \dots}}{\int \mathcal{D}\tilde{\phi} e^{i \dots}} D^{-1} + \frac{i}{2} D^{-1} = \frac{i}{2} D^{-1} [-G + D] D^{-1}$$

$$\underline{\underline{\underline{G = D + D\Pi D + D\Pi D\Pi D + \dots}}}} = -\frac{i}{2} [\Pi + \Pi D \Pi + \dots] \text{ 连接图} \Rightarrow \underline{\underline{\bar{\Gamma}_2 \text{ 是一粒子不可约的}}}$$

## 利用有效作用的圈图展开计算路径积分

$$e^{iW[J]} = \int \mathcal{D}\phi e^{i \int d^4x (\mathcal{L} + J\phi)} \quad \underline{\text{有效作用量}} : \Gamma[\hat{\phi}] \equiv W[J] - \int d^4x J(x)\hat{\phi}(x) \quad \frac{\delta\Gamma[\hat{\phi}]}{\delta\hat{\phi}(x)} = -J(x)$$

$$\Gamma[\hat{\phi}] = S[\hat{\phi}] + \frac{i}{2} \text{Tr} \ln i\mathcal{D}^{-1}(\hat{\phi}) + \bar{\Gamma}_2 \quad \bar{\Gamma}_2 = \sum_{n=2}^{\infty} \Gamma_n[\hat{\phi}]$$

$\Gamma_n[\hat{\phi}] =$  以  $\mathcal{D}(\phi_{cl}; x, y)$  为传播子,  $I_{\text{int}}[\hat{\phi}, \tilde{\phi}]$  为相互作用顶角的所有一粒子不可约  $n$  圈图

路径积分的圈图计算:  $\hat{\phi} \stackrel{J=0}{=} \langle \phi \rangle$

$$e^{iW[0]} = e^{i\Gamma[\langle \phi \rangle]} = \int \mathcal{D}\phi e^{iS[\phi]} \quad \frac{\delta\Gamma[\langle \phi \rangle]}{\delta\langle \phi(x) \rangle} = 0$$

$$\Gamma[\langle \phi \rangle] = S[\langle \phi \rangle] + \frac{i}{2} \text{Tr} \ln \frac{\delta^2 S[\langle \phi \rangle]}{\delta\langle \phi(x) \rangle \delta\langle \phi(y) \rangle} + \bar{\Gamma}_2 \quad \bar{\Gamma}_2 = \sum_{n=2}^{\infty} \Gamma_n[\langle \phi \rangle]$$

$\Gamma_n[\hat{\phi}] =$  以  $[\frac{\delta^2 S[\langle \phi \rangle]}{\delta\langle \phi(x) \rangle \delta\langle \phi(y) \rangle}]^{-1}$  为传播子,  $I_{\text{int}}[\langle \phi \rangle, \tilde{\phi}]$  为相互作用顶角的所有一粒子不可约  $n$  圈图

$I_{\text{int}}[\langle \phi \rangle, \tilde{\phi}]$  是  $S[\langle \phi \rangle + \tilde{\phi}]$  中按  $\tilde{\phi}$  幂次展开三次和三次以上项之和

有效势  $\Gamma[\hat{\phi}] = S[\hat{\phi}] + \frac{i}{2} \text{Tr} \ln i\mathcal{D}^{-1}(\hat{\phi}) + \bar{\Gamma}_2 \stackrel{\text{平移不变}}{\text{}} - V_{\text{eff}}[\hat{\phi}] \int d^4x$

$$V_{\text{eff}} = V(\hat{\phi}) + V_1(\hat{\phi}) + V_2(\hat{\phi}) + \dots \quad V_1(\hat{\phi}) = -\frac{i}{2} \int \frac{d^4p}{(2\pi)^4} \text{tr} \ln i\mathcal{D}^{-1}(\hat{\phi}; p) \quad V_2(\hat{\phi}) = i \left\langle e^{i \int d^4x \mathcal{L}_{\text{int}}(\hat{\phi}, \tilde{\phi})} \right\rangle_{\text{IPI}}$$

$$i\mathcal{D}^{-1}(\hat{\phi}; x, y) \stackrel{\text{平移不变}}{\text{}} \int \frac{d^4p}{(2\pi)^4} e^{-ip \cdot (x-y)} i\mathcal{D}^{-1}(\hat{\phi}; p) = i\mathcal{D}^{-1}(\hat{\phi}; i\partial_x) \delta(x-y)$$

$$\int d^4z [A(i\partial_x) \delta(x-z)] [B(i\partial_z) \delta(z-y)] = \int d^4z [A(i\partial_x) \delta(x-z)] [B(-i\partial_y) \delta(z-y)] = A(i\partial_x) B(i\partial_x) \delta(x-y)$$

$$\int d^4z_1 \dots d^4z_{n-1} [A_1(i\partial_x) \delta(x-z_1)] [A_2(i\partial_{z_1}) \delta(z_1-z_2)] \dots [A_n(i\partial_{z_{n-1}}) \delta(z_{n-1}-y)] = A_1(i\partial_x) \dots A_n(i\partial_x) \delta(x-y)$$

$$[\ln i\mathcal{D}^{-1}(\hat{\phi})](x, y) = [\ln i\mathcal{D}^{-1}(\hat{\phi}; i\partial_x)] \delta(x-y)$$

$$\text{Tr} \ln i\mathcal{D}^{-1}(\hat{\phi}) = \int d^4x \text{tr} [\ln i\mathcal{D}^{-1}(\hat{\phi})](x, x) = \int d^4x \int \frac{d^4p}{(2\pi)^4} \text{tr} \ln i\mathcal{D}^{-1}(\hat{\phi}; p)$$

有效势可以相差一个与 $\hat{\phi}$ 无关的常数！  $V_1(\hat{\phi}) = -\frac{i}{2} \int \frac{d^4p}{(2\pi)^4} \ln \frac{\det[i\mathcal{D}^{-1}(\hat{\phi}; p)]}{\det[i\mathcal{D}^{-1}(0; p)]}$

对费米子 $V_1$ 中的系数  $-\frac{i}{2}$  应该被换为  $+i$ ！因自由玻色和费米场的积分分别给出  $\text{Det}^{-\frac{1}{2}}$  和  $\text{Det}$

$$i\mathcal{D}^{-1}(\hat{\phi}; x, y) \Rightarrow iS^{-1}(\hat{\psi}, \hat{\psi}) \equiv \frac{\delta S[\hat{\psi}, \hat{\psi}]}{\delta \hat{\psi}(x) \delta \hat{\psi}(y)}$$

## 关于玻色子与费米子对有效势贡献的讨论

♣ 玻色子与费米子对有效势的一阶贡献的符号相反

◇ 若玻色子倾向产生自发破缺,则费米子倾向破坏自发破缺,反之亦然!

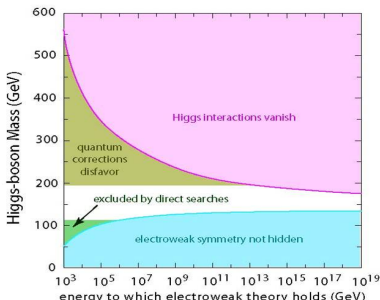
♡ 由此从势的稳定性给出对标准模型中的Higgs质量的限制! 两圈图计算

♠ 若玻色子与费米子之间达到某种平衡,也就是具有超对称性:

🔪 有效势有可能不受高阶量子修正影响!

✘ 导致体系无动力学自发破坏!

⚡ 还导致理论的有效势可精确计算!



## S.Coleman and E.Weinberg, Phys.Rev.D7,1888(1973)

考虑纯由量子修正产生的对称性自发破缺当初未用Jackiw的方法

- ▶ 任意性小,预言性高
- ▶ 量子修正的重要性

$$O(2) \text{ } \sigma \text{ 模型: } S = \int d^4x \mathcal{L} = \int d^4x [\frac{1}{2}(\partial_\mu \sigma \partial^\mu \sigma + \partial_\mu \pi \partial^\mu \pi) - \frac{\lambda}{4!}(\sigma^2 + \pi^2)^2]$$

对应原来的无自发破缺情形:  $\kappa = -\mu^2 \stackrel{\frac{\kappa}{2}(\sigma^2 + \pi^2)}{====} \Rightarrow \kappa = 0$ 

$$V_{\text{eff}} = V_0 + V_1 \quad V_0 = -\frac{\lambda}{4!}(\sigma^2 + \pi^2)^2 \quad V_1 = -\frac{i}{2} \int \frac{d^4p}{(2\pi)^4} \ln \frac{\det[i\mathcal{D}^{-1}(\hat{\sigma}, \hat{\pi}; p)]}{\det[i\mathcal{D}^{-1}(0, 0; p)]}$$

$$i\mathcal{D}_{\sigma\sigma}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = \frac{\delta^2 S}{\delta\sigma(x)\delta\sigma(y)} = -(\partial_x^2 + \frac{\lambda}{2}\hat{\sigma}^2 + \frac{\lambda}{6}\hat{\pi}^2)\delta(x-y)$$

$$i\mathcal{D}_{\sigma\pi}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = \frac{\delta^2 S}{\delta\sigma(x)\delta\pi(y)} = i\mathcal{D}_{\pi\sigma}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = -\frac{\lambda}{3}\hat{\sigma}\hat{\pi}\delta(x-y)$$

$$i\mathcal{D}_{\pi\pi}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = \frac{\delta^2 S}{\delta\pi(x)\delta\pi(y)} = -(\partial_x^2 + \frac{\lambda}{2}\hat{\pi}^2 + \frac{\lambda}{6}\hat{\sigma}^2)\delta(x-y)$$

$O(2)$   $\sigma$ 模型:  $S = \int d^4x \mathcal{L} = \int d^4x [\frac{1}{2}(\partial_\mu \sigma \partial^\mu \sigma + \partial_\mu \pi \partial^\mu \pi) - \frac{\lambda}{4!}(\sigma^2 + \pi^2)^2]$

$$V_{\text{eff}} = V_0 + V_1 \quad V_0 = -\frac{\lambda}{4!}(\sigma^2 + \pi^2)^2 \quad V_1 = -\frac{i}{2} \int \frac{d^4p}{(2\pi)^4} \ln \frac{\det[i\mathcal{D}^{-1}(\hat{\sigma}, \hat{\pi}; p)]}{\det[i\mathcal{D}^{-1}(0, 0; p)]}$$

$$i\mathcal{D}^{-1}(\hat{\sigma}, \hat{\pi}; p) = \begin{pmatrix} i\mathcal{D}_{\sigma\sigma}^{-1}(\hat{\sigma}, \hat{\pi}; p) & i\mathcal{D}_{\sigma\pi}^{-1}(\hat{\sigma}, \hat{\pi}; p) \\ i\mathcal{D}_{\pi\sigma}^{-1}(\hat{\sigma}, \hat{\pi}; p) & i\mathcal{D}_{\pi\pi}^{-1}(\hat{\sigma}, \hat{\pi}; p) \end{pmatrix} = \begin{pmatrix} p^2 - \frac{\lambda}{2}\hat{\sigma}^2 - \frac{\lambda}{6}\hat{\pi}^2 & -\frac{\lambda}{3}\hat{\sigma}\hat{\pi} \\ -\frac{\lambda}{3}\hat{\sigma}\hat{\pi} & p^2 - \frac{\lambda}{2}\hat{\pi}^2 - \frac{\lambda}{6}\hat{\sigma}^2 \end{pmatrix}$$

$$\det[i\mathcal{D}^{-1}(\hat{\sigma}, \hat{\pi}; p)] = (p^2 - \frac{\lambda}{2}\hat{\sigma}^2 - \frac{\lambda}{6}\hat{\pi}^2)(p^2 - \frac{\lambda}{2}\hat{\pi}^2 - \frac{\lambda}{6}\hat{\sigma}^2) - \frac{\lambda^2}{9}\hat{\sigma}^2\hat{\pi}^2 = [p^2 - \frac{\lambda}{2}(\hat{\sigma}^2 + \hat{\pi}^2)][p^2 - \frac{\lambda}{6}(\hat{\pi}^2 + \hat{\sigma}^2)]$$

$$V_1 = -\frac{i}{2} \int \frac{d^4p}{(2\pi)^4} \left[ \ln(1 - \frac{\lambda}{2p^2}\hat{\phi}^2) + \ln(1 - \frac{\lambda}{6p^2}\hat{\phi}^2) \right] \quad \hat{\phi} \equiv \hat{\sigma}^2 + \hat{\pi}^2$$

$$\stackrel{\text{Wick Rotation}}{=} -\frac{i}{2} \frac{i\pi^2}{(2\pi)^4} \lim_{\Lambda \rightarrow \infty} \int_0^{\Lambda^2} p_E^2 dp_E^2 \left[ \ln(1 + \frac{\lambda}{2p_E^2}\hat{\phi}^2) + \ln(1 + \frac{\lambda}{6p_E^2}\hat{\phi}^2) \right]$$

在有平移不变的情形下,应用动量截断正规化并不破坏规范对称性!

$$\int_0^{\Lambda^2} x dx \ln(1 + \frac{a}{x}) = \frac{x^2}{2} \ln(1 + \frac{a}{x}) \Big|_0^{\Lambda^2} + \frac{1}{2} \int_0^{\Lambda^2} \frac{a}{1 + \frac{a}{x}} dx = a\Lambda^2 + \frac{a^2}{2} (\ln \frac{a}{\Lambda^2} - \frac{1}{2})$$

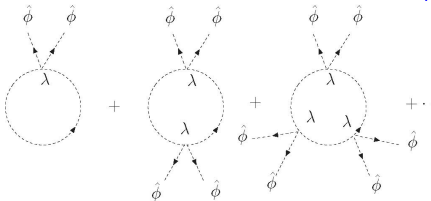
$$V_1 = \frac{1}{32\pi^2} \left[ \frac{\lambda}{2}\hat{\phi}^2\Lambda^2 + \frac{\lambda^2\hat{\phi}^4}{8} (\ln \frac{\lambda}{2}\hat{\phi}^2 - \frac{1}{2}) + \frac{\lambda}{6}\hat{\phi}^2\Lambda^2 + \frac{\lambda^2\hat{\phi}^4}{72} (\ln \frac{\lambda}{6}\hat{\phi}^2 - \frac{1}{2}) \right]$$

$O(2)$   $\sigma$ 模型:  $S = \int d^4x \mathcal{L} = \int d^4x [\frac{1}{2}(\partial_\mu \sigma \partial^\mu \sigma + \partial_\mu \pi \partial^\mu \pi) - \frac{\lambda}{4!}(\sigma^2 + \pi^2)^2]$

$$V_{\text{eff}} = V_0 + V_1 \quad V_0 = -\frac{\lambda}{4!}(\sigma^2 + \pi^2)^2 \quad V_1 = \frac{1}{32\pi^2} \left[ \frac{2\lambda}{3} \hat{\phi}^2 \Lambda^2 + \frac{\lambda^2 \hat{\phi}^4}{8} \left( \ln \frac{\frac{\lambda}{2} \hat{\phi}^2}{\Lambda^2} - \frac{1}{2} \right) + \frac{\lambda^2 \hat{\phi}^4}{72} \left( \ln \frac{\frac{\lambda}{6} \hat{\phi}^2}{\Lambda^2} - \frac{1}{2} \right) \right]$$

早期的费曼图求和 每个图都有红外发散, 将所有阶图求和可消去

$$\ln\left(1 - \frac{\lambda}{p^2} \hat{\phi}^2\right) = -\frac{\lambda}{p^2} \hat{\phi}^2 - \frac{1}{2} \frac{\lambda}{p^2} \hat{\phi}^2 \frac{\lambda}{p^2} \hat{\phi}^2 - \frac{1}{3} \frac{\lambda}{p^2} \hat{\phi}^2 \frac{\lambda}{p^2} \hat{\phi}^2 \frac{\lambda}{p^2} \hat{\phi}^2 + \dots$$



**Jackiw**的公式实现了对无穷多费曼图的求和!

重整化: 采用抵消项

$$V_1 \stackrel{\text{重整化}}{=} \frac{1}{32\pi^2} \left[ \frac{2\lambda}{3} \hat{\phi}^2 \Lambda^2 + \frac{\lambda^2 \hat{\phi}^4}{8} \left( \ln \frac{\frac{\lambda}{2} \hat{\phi}^2}{\Lambda^2} - \frac{1}{2} \right) + \frac{\lambda^2 \hat{\phi}^4}{72} \left( \ln \frac{\frac{\lambda}{6} \hat{\phi}^2}{\Lambda^2} - \frac{1}{2} \right) \right] - \frac{1}{2} C_1 \hat{\phi}^2 - \frac{1}{4!} C_2 \hat{\phi}^4$$

归一化条件:  $\xrightarrow{V_0 = \frac{\lambda}{4!} \hat{\phi}^4 \text{ 裸常数不需量子修正}}$   $\frac{d^2 V_{\text{eff}}}{d\hat{\phi}^2} \Big|_{\hat{\phi}=0} = 0$   $\frac{d^4 V_{\text{eff}}}{d\hat{\phi}^4} \Big|_{\hat{\phi}=M} = \lambda \equiv \lambda(M)$   $\leftarrow$  无量纲理论通过归一化引入量纲

$$C_1 = \frac{\lambda \Lambda^2}{24\pi^2} \quad C_2 = \frac{55\lambda^2}{144\pi^2} + \frac{3\lambda^2}{32\pi^2} \ln \frac{\lambda M^2}{\Lambda^2} + \frac{\lambda^2}{96\pi^2} \ln \frac{\lambda M^2}{\Lambda^2} \quad V_{\text{eff}} = \frac{\lambda}{4!} \hat{\phi}^4 + \frac{5\lambda^2 \hat{\phi}^4}{1152\pi^2} \left( \ln \frac{\hat{\phi}^2}{M^2} - \frac{25}{6} \right)$$

$$\text{展开收敛条件: } |\lambda| < 1 \quad \left| \lambda \ln \frac{\hat{\phi}^2}{M^2} \right| < 1$$



$$O(2) \sigma \text{模型: } S = \int d^4x \mathcal{L} = \int d^4x \left[ \frac{1}{2} (\partial_\mu \sigma \partial^\mu \sigma + \partial_\mu \pi \partial^\mu \pi) - \frac{\lambda}{4!} (\sigma^2 + \pi^2)^2 \right]$$

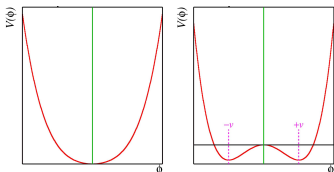
$$\text{归一化条件: } \xrightarrow{v_0 = \frac{\lambda}{4!} \hat{\phi}^4 \text{ 裸常数不需量子修正}} \left. \frac{d^2 V_{\text{eff}}}{d\hat{\phi}^2} \right|_{\hat{\phi}=0} = 0 \quad \left. \frac{d^4 V_{\text{eff}}}{d\hat{\phi}^4} \right|_{\hat{\phi}=M} = \lambda \equiv \lambda(M) \leftarrow \text{无量纲理论通过归一化引入量纲}$$

$$V_{\text{eff}} = \frac{\lambda}{4!} \hat{\phi}^4 + \frac{5\lambda^2 \hat{\phi}^4}{1152\pi^2} \left( \ln \frac{\hat{\phi}^2}{M^2} - \frac{25}{6} \right) \quad \text{展开收敛条件: } |\lambda| < 1 \quad \left| \lambda \ln \frac{\hat{\phi}^2}{M^2} \right| < 1$$

$$\text{尺度变换性质: } V_{\text{eff}} = \frac{\lambda'}{4!} \hat{\phi}^4 + \frac{5\lambda'^2 \hat{\phi}^4}{1152\pi^2} \left( \ln \frac{\hat{\phi}^2}{M'^2} - \frac{25}{6} \right)$$

$$\lambda(M) \xrightarrow{M \rightarrow M'} \lambda' \equiv \lambda(M') = \left. \frac{d^4 V_{\text{eff}}}{d\hat{\phi}^4} \right|_{\hat{\phi}=M'} = \lambda + \frac{5\lambda^2}{48\pi^2} \ln \frac{M'^2}{M^2}$$

圈图对数项在小大  $\hat{\phi}$  区降低升高有效势



$$0 = \left. \frac{dV_{\text{eff}}}{d\hat{\phi}} \right|_{\hat{\phi}=\langle\phi\rangle} = \lambda \langle\phi\rangle^3 \left[ \frac{1}{6} + \frac{5\lambda}{288\pi^2} \ln \frac{\langle\phi\rangle^2}{M^2} - \frac{55\lambda}{964\pi^2} \right] \Rightarrow \langle\phi\rangle = 0, Me^{-\frac{24\pi^2}{5\lambda} + \frac{11}{6}} \quad \text{与 } M \text{ 无关}$$

$$V_{\text{eff}}(\hat{\phi} = 0) = 0 \quad V_{\text{eff}}(\hat{\phi} = Me^{-\frac{24\pi^2}{5\lambda} + \frac{11}{6}}) = -\frac{5\lambda^2 \langle\phi\rangle^4}{2304\pi^2}$$

耦合常数的负幂次: 非微扰

判断一个理论是否发生对称性自发破缺, 只考虑数图可能会出错, 应该计算圈图!

维数转移:  $\lambda(M = \langle\phi\rangle) = \frac{144}{55} \pi^2$  不合理, 数值并不可靠!

## 标量QED

$$\phi = \begin{pmatrix} \sigma \\ \pi \end{pmatrix} \quad \text{两个无量纲参数}$$

$$S = \int d^4x \mathcal{L} = \int d^4x \left[ -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{1}{2\alpha} (\partial_\mu A^\mu)^2 + \frac{1}{2} (\partial_\mu \sigma + e A_\mu \pi)^2 + \frac{1}{2} (\partial_\mu \pi - e A_\mu \sigma)^2 - \frac{\lambda}{4!} (\sigma^2 + \pi^2)^2 \right]$$

$$\frac{\delta W}{\delta J} = \hat{\phi} \quad \frac{\delta W}{\delta J_\mu} \stackrel{J_\mu A^\mu}{=} \hat{A}^\mu \quad \text{洛伦兹对称性禁戒其有真空期望值} \quad V_{\text{eff}}(\hat{\phi}) \equiv V_{\text{eff}}(\hat{\phi}, \hat{A}^\mu = 0)$$

$$i\mathcal{D}_{\mu\nu}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = \left. \frac{\delta^2 S}{\delta A^\mu(x) \delta A^\nu(y)} \right|_{\substack{\sigma=\hat{\sigma} \\ \pi=\hat{\pi}}} = [g_{\mu\nu} \partial_x^2 - (1 - \frac{1}{\alpha}) \partial_\mu \partial_\nu + e^2 g_{\mu\nu} (\hat{\sigma}^2 + \hat{\pi}^2)] \delta(x - y)$$

$$i\mathcal{D}_{\mu\sigma}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = \left. \frac{\delta^2 S}{\delta A^\mu(x) \delta \sigma(y)} \right|_{\substack{\sigma=\hat{\sigma} \\ \pi=\hat{\pi}}} = 2e\hat{\pi} \partial_\mu \delta(x - y) \quad i\mathcal{D}_{\sigma\pi}^{-1}, i\mathcal{D}_{\pi\pi}^{-1}, i\mathcal{D}_{\sigma\pi}^{-1} \text{ 与前一一样}$$

$$i\mathcal{D}_{\mu\pi}^{-1}(\hat{\sigma}, \hat{\pi}; x, y) = \left. \frac{\delta^2 S}{\delta A^\mu(x) \delta \pi(y)} \right|_{\substack{\sigma=\hat{\sigma} \\ \pi=\hat{\pi}}} = -2e\hat{\sigma} \partial_\mu \delta(x - y) \quad \text{为方便计算取特殊坐标系: } p^\mu = (p^0, 0, 0, 0)$$

标量QED  $\phi = \begin{pmatrix} \sigma \\ \pi \end{pmatrix}$  两个无量纲参数

$$S = \int d^4x \mathcal{L} = \int d^4x \left[ -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} - \frac{1}{2\alpha} (\partial_\mu A^\mu)^2 + \frac{1}{2} (\partial_\mu \sigma + e A_\mu \pi)^2 + \frac{1}{2} (\partial_\mu \pi - e A_\mu \sigma)^2 - \frac{\lambda}{4!} (\sigma^2 + \pi^2)^2 \right]$$

$$\det[i\mathcal{D}^{-1}(\hat{\sigma}, \hat{\pi}; p)] \stackrel{p^\mu = (p^0, 0, 0, 0)}{=} \begin{vmatrix} i\mathcal{D}_{11}^{-1} & 0 & 0 & 0 & 0 & 0 \\ 0 & i\mathcal{D}_{22}^{-1} & 0 & 0 & 0 & 0 \\ 0 & 0 & i\mathcal{D}_{33}^{-1} & 0 & 0 & 0 \\ 0 & 0 & 0 & i\mathcal{D}_{00}^{-1} & i\mathcal{D}_{0\sigma}^{-1} & i\mathcal{D}_{0\pi}^{-1} \\ 0 & 0 & 0 & i\mathcal{D}_{\sigma 0}^{-1} & i\mathcal{D}_{\sigma\sigma}^{-1} & i\mathcal{D}_{\sigma\pi}^{-1} \\ 0 & 0 & 0 & i\mathcal{D}_{\pi 0}^{-1} & i\mathcal{D}_{\pi\sigma}^{-1} & i\mathcal{D}_{\pi\pi}^{-1} \end{vmatrix} = i\mathcal{D}_{11}^{-1} i\mathcal{D}_{22}^{-1} i\mathcal{D}_{33}^{-1}$$

$$\begin{aligned} & \times [i\mathcal{D}_{00}^{-1}(i\mathcal{D}_{\sigma\sigma}^{-1}i\mathcal{D}_{\pi\pi}^{-1} - i\mathcal{D}_{\sigma\pi}^{-1}i\mathcal{D}_{\pi\sigma}^{-1}) - i\mathcal{D}_{0\sigma}^{-1}(i\mathcal{D}_{\sigma 0}^{-1}i\mathcal{D}_{\pi\pi}^{-1} - i\mathcal{D}_{\pi 0}^{-1}i\mathcal{D}_{\sigma\pi}^{-1}) + i\mathcal{D}_{0\pi}^{-1}(i\mathcal{D}_{\sigma 0}^{-1}i\mathcal{D}_{\pi\sigma}^{-1} - i\mathcal{D}_{\pi 0}^{-1}i\mathcal{D}_{\sigma\sigma}^{-1})] \\ & \stackrel{(p^0)^2 \Rightarrow p^2}{=} (-p^2 + e^2 \hat{\phi}^2)^3 \left[ \left(-\frac{1}{\alpha} p^2 + e^2 \hat{\phi}^2\right) \left(-p^2 + \frac{\lambda}{2} \hat{\phi}^2\right) \left(-p^2 + \frac{\lambda}{6} \hat{\phi}^2\right) - 4e^2 \hat{\phi}^2 p^2 \left(-p^2 + \frac{\lambda}{2} \hat{\phi}^2\right) \right] \end{aligned}$$

$$\frac{\det[i\mathcal{D}^{-1}(\hat{\sigma}, \hat{\pi}; p)]}{\det[i\mathcal{D}^{-1}(0, 0; p)]} = \left(1 - \frac{e^2 \hat{\phi}^2}{p^2}\right)^3 \left[ \left(1 - \alpha \frac{e^2 \hat{\phi}^2}{p^2}\right) \left(1 - \frac{\lambda \hat{\phi}^2}{2 p^2}\right) \left(1 - \frac{\lambda \hat{\phi}^2}{6 p^2}\right) - 4\alpha \frac{e^2 \hat{\phi}^2}{p^2} \left(1 - \frac{\lambda \hat{\phi}^2}{2 p^2}\right) \right]$$

有效势一般说是规范依赖的,只在真空极小点处是规范无关的!

R.Fukuda and T.Kugo, Phys. Rev. D13,3469(1974)

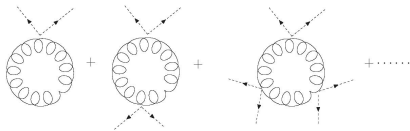
## 标量QED

$$\phi = \begin{pmatrix} \sigma \\ \pi \end{pmatrix} \quad \text{两个无量纲参数}$$

$$\frac{\det[iD^{-1}(\hat{\sigma}, \hat{\pi}; p)]}{\det[iD^{-1}(0, 0; p)]} \stackrel{\text{Landau规范 } \alpha=0}{=} \left(1 - \frac{e^2 \hat{\phi}^2}{p^2}\right)^3 \left(1 - \frac{\frac{\lambda}{2} \hat{\phi}^2}{p^2}\right) \left(1 - \frac{\frac{\lambda}{6} \hat{\phi}^2}{p^2}\right) \quad e=0 \text{ 回到 } O(2) \text{ } \sigma \text{ 模型}$$

$$V_1(\hat{\phi}) = \frac{2\lambda + 9e^2}{96\pi^2} \hat{\phi}^2 \Lambda^2 - \frac{5}{18} \frac{\lambda^2 + 3e^4}{128\pi^2} \hat{\phi}^4 + \frac{\lambda^2 \hat{\phi}^4}{256\pi^2} \ln \frac{\lambda \hat{\phi}^2}{\Lambda^2}$$

$$+ \frac{\lambda^2 \hat{\phi}^4}{2304\pi^2} \ln \frac{\lambda \hat{\phi}^2}{\Lambda^2} + \frac{3e^4 \hat{\phi}^4}{64\pi^2} \ln \frac{e^2 \hat{\phi}^2}{\Lambda^2} - \frac{1}{2} C_1 \hat{\phi}^2 - \frac{\lambda}{4!} C_2 \hat{\phi}^4$$



$$\stackrel{\text{裸常数不需量子修正}}{=} \rightarrow \left. \frac{d^2 V_{\text{eff}}}{d\hat{\phi}^2} \right|_{\hat{\phi}=0} = 0 \quad \left. \frac{d^4 V_{\text{eff}}}{d\hat{\phi}^4} \right|_{\hat{\phi}=M} = \lambda \equiv \lambda(M) \quad \Rightarrow \quad C_1 = \frac{2\lambda + 9e^2}{48\pi^2} \Lambda^2$$

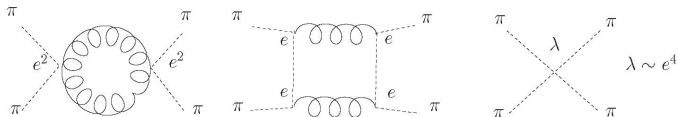
$$C_2 = \frac{11}{8\pi^2} \left( \frac{5}{18\pi^2} \lambda^2 + 3e^4 \right) + \frac{3\lambda^2}{32\pi^2} \ln \frac{\lambda M^2}{\Lambda^2} + \frac{\lambda^2}{96\pi^2} \ln \frac{\lambda M^2}{\Lambda^2} + \frac{9e^4}{8\pi^2} \ln \frac{e^2 M^2}{\Lambda^2}$$

$$V_{\text{eff}}(\hat{\phi}) = \frac{\lambda}{4!} \hat{\phi}^4 + \left( \frac{5\lambda^2}{1152\pi^2} + \frac{3e^4}{64\pi^2} \right) \hat{\phi}^4 \left( \ln \frac{\hat{\phi}^2}{M^2} - \frac{25}{6} \right)$$

## 标量QED

$$\phi = \begin{pmatrix} \sigma \\ \pi \end{pmatrix} \quad \text{两个无量纲参数}$$

$\pi\pi$ 散射告诉我们:



$$V_{\text{eff}}(\hat{\phi}) = \frac{\lambda}{4!} \hat{\phi}^4 + \left( \frac{5\lambda^2}{1152\pi^2} + \frac{3e^4}{64\pi^2} \right) \hat{\phi}^4 \left( \ln \frac{\hat{\phi}^2}{M^2} - \frac{25}{6} \right) \cong \frac{\lambda}{4!} \hat{\phi}^4 + \frac{3e^4}{64\pi^2} \hat{\phi}^4 \left( \ln \frac{\hat{\phi}^2}{M^2} - \frac{25}{6} \right)$$

$$0 = \frac{dV_{\text{eff}}}{d\hat{\phi}} \Big|_{\hat{\phi}=\langle\phi\rangle} = \langle\phi\rangle^3 \left[ \frac{\lambda}{6} - \frac{11e^4}{16\pi^2} + 3 \ln \frac{\langle\phi\rangle^2}{M^2} \right] \Rightarrow \lambda \stackrel{\langle\phi\rangle=M \neq 0}{=} \frac{33}{8\pi^2} e^4 \quad V_{\text{eff}}(\hat{\phi}) = \frac{3e^4}{64\pi^2} \hat{\phi}^4 \left( \ln \frac{\hat{\phi}^2}{\langle\phi\rangle^2} - \frac{1}{2} \right)$$

两个解:  $V_{\text{eff}}[\langle\phi\rangle = 0] = 0 \quad V_{\text{eff}}[\langle\phi\rangle = M \neq 0] = -\frac{3e^4}{128\pi^2} \langle\phi\rangle^4$

$\hat{\phi} \neq 0 \stackrel{\text{宇称不破坏}}{\Rightarrow} \langle\sigma\rangle = \langle\phi\rangle \neq 0, \langle\pi\rangle = 0 \Rightarrow M_A^2 = e^2 \langle\sigma\rangle^2$  电磁规范对称性自发破缺, 光子获得质量

$$\sigma = \langle\sigma\rangle + \tilde{\sigma} \quad m_{\tilde{\sigma}}^2 = \frac{d^2 V_{\text{eff}}}{d\hat{\phi}^2} \Big|_{\hat{\phi}=\langle\phi\rangle} = \frac{3e^4}{8\pi^2} \langle\sigma\rangle^2 = \frac{3}{2\pi} \left( \frac{e^2}{4\pi} \right) M_A^2$$

现在的自发破缺解不限制一定要取大的耦合常数!

## 进一步推广到 $SU(2) \times U(1)$ 理论

期望重现标量QED的结果:

- ▶ 规范对称性被自发破缺
- ▶ 给出耦合常数之间的关联
- ▶ 给出由自发破缺而获得的标量粒子质量和规范粒子质量之间的关联

经过复杂计算得到:

$$m_H^2 = \frac{3}{32\pi^2} [2g^2 M_W^2 + (g^2 + g'^2) M_Z^2] \xrightarrow{\tan \theta_W = \frac{g'}{g}, e = g \sin \theta_W} 9.4 \sim 10.4 \text{ GeV}$$

实际 LEP II:  $m_H > 114 \text{ GeV}$

此质量应是标准模型中的Higgs质量最小值!  $\mu^2 = 0$  仍有此结果

虽然对标准模型并不成功,但理论想法会有很多应用!

- ▶ 大统一 Gell-mann, Slansky : 考虑一圈修正后,破缺倾向于保持最大子对称性
- ▶ 宇宙学
- ▶ 确定精细结构常数, .....

D.J.Gross and A.Nevue, Phys. Rev. D10,3235(1974)

寻找与QCD类似又严格可解的模型: 1 + 1 维时空

- ▶ 可重整
- ▶ 色自由度直接关系相互作用
- ▶ 渐进自由
- ▶ 手征对称性自发破缺

$$\mathcal{L} = \bar{\psi}i\partial\psi + \frac{1}{2}g^2(\bar{\psi}\psi)^2 \quad \text{好像势无下界?} \quad \psi = \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_N \end{pmatrix} \quad \text{2N个分量} \quad \bar{\psi}\psi \equiv \sum_a \bar{\psi}_a\psi_a$$

它对应积掉胶子场的QCD理论!  $\dim(\psi) = \frac{1}{2} \quad \dim(g) = 0$

拉氏量具有的对称性 $U(N)$ 对应QCD的色对称性联系动力学,不应发生破缺!

**Coleman定理:**  $D \leq 2$  维时空中不存在Goldstone玻色子!

存在分立对称性 对应QCD的手征对称性:  $\psi \rightarrow \gamma_5\psi = e^{i\frac{\pi}{2}}\gamma_5\psi$

$$\bar{\psi}\psi \rightarrow (\gamma_5\psi)^\dagger \gamma^0 \gamma_5\psi = -\bar{\psi}\psi \quad \bar{\psi}\gamma^\mu\psi \rightarrow (\gamma_5\psi)^\dagger \gamma^0 \gamma^\mu \gamma_5\psi = \bar{\psi}\gamma^\mu\psi$$

存在分立对称性 对应QCD的手征对称性:  $\psi \rightarrow \gamma_5 \psi = e^{i\frac{\pi}{2}\gamma_5} \psi$

$$\mathcal{L} = \bar{\psi} i \not{\partial} \psi + \frac{1}{2} g^2 (\bar{\psi} \psi)^2 \quad \psi = \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_N \end{pmatrix} \quad \text{2N个分量} \quad \bar{\psi} \psi \equiv \sum_a \bar{\psi}_a \psi_a$$

$$\bar{\psi} \psi \rightarrow (\gamma_5 \psi)^\dagger \gamma^0 \gamma_5 \psi = -\bar{\psi} \psi \quad \bar{\psi} \gamma^\mu \psi \rightarrow (\gamma_5 \psi)^\dagger \gamma^0 \gamma^\mu \gamma_5 \psi = \bar{\psi} \gamma^\mu \psi$$

$$\gamma^0 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \gamma^1 = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \quad \gamma_5 = \gamma^0 \gamma^1 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$P_L \equiv \frac{1 - \gamma_5}{2} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad P_R \equiv \frac{1 + \gamma_5}{2} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu} \quad \{\gamma_5, \gamma_\mu\} = 0 \quad \mu = 0, 1$$

需要研究描述  $\bar{\psi}(x)\psi(x)$  的有效势理论

描述  $\bar{\psi}(x)\psi(y)$  的有效势理论: [Cornwell, Jackiw, Tomboulis, Phys. Rev. D10, 2428 \(1974\)](#)

它导致积分方程!



存在分立对称性 对应QCD的手征对称性:  $\psi \rightarrow \gamma_5 \psi = e^{i\frac{\pi}{2}} \gamma_5 \psi$

$$\mathcal{L} = \bar{\psi} i \not{\partial} \psi + \frac{1}{2} g^2 (\bar{\psi} \psi)^2 \quad \psi = \begin{pmatrix} \psi_1 \\ \vdots \\ \psi_N \end{pmatrix} \quad \text{2N个分量} \quad \bar{\psi} \psi \equiv \sum_a \bar{\psi}_a \psi_a$$

$$\bar{\psi} \psi \rightarrow (\gamma_5 \psi)^\dagger \gamma^0 \gamma_5 \psi = -\bar{\psi} \psi \quad \bar{\psi} \gamma^\mu \psi \rightarrow (\gamma_5 \psi)^\dagger \gamma^0 \gamma^\mu \gamma_5 \psi = \bar{\psi} \gamma^\mu \psi$$

建立生成泛函:  $Z[K] = e^{W[K]} = \int \mathcal{D}\psi \mathcal{D}\bar{\psi} e^{i \int d^2x [\mathcal{L} + K g \bar{\psi} \psi]}$

$$\int \mathcal{D}\sigma e^{-\frac{i}{2} \int d^2x (\sigma - g \bar{\psi} \psi)^2} = \int \mathcal{D}(\sigma - g \bar{\psi} \psi) e^{-\frac{i}{2} \int d^2x (\sigma - g \bar{\psi} \psi)^2} = \int \mathcal{D}\sigma e^{-\frac{i}{2} \int d^2x \sigma^2} = \text{常数}$$

$$Z[K] = \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i \int d^2x [\mathcal{L} - \frac{1}{2} (\sigma - g \bar{\psi} \psi)^2 + g K \bar{\psi} \psi]} = \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i \int d^2x [\bar{\psi} (i \not{\partial} + g \sigma + g K) \psi - \frac{1}{2} \sigma^2]}$$

$$\mathcal{L}_\sigma = \bar{\psi} (i \not{\partial} + g \sigma) \psi - \frac{1}{2} \sigma^2 \quad \sigma: \text{辅助场} \quad \text{无动能项} \quad \xrightarrow{\text{经典解}} \quad \underline{\sigma = g \bar{\psi} \psi} \quad \mathcal{L}_\sigma \Big|_{\sigma = g \bar{\psi} \psi} = \mathcal{L}$$

$$Z[K] = \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i \int d^2x [\bar{\psi} (i \not{\partial} + g \sigma) \psi - \frac{1}{2} (\sigma - K)^2]} = e^{-i \frac{K^2}{2}} \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i \int d^2x [\bar{\psi} (i \not{\partial} + g \sigma) \psi - \frac{1}{2} \sigma^2 + K \sigma]}$$

$$\langle g \bar{\psi}(x) \psi(x) \rangle_{\mathcal{L}} = \left. \frac{\delta W[K]}{\delta K(x)} \right|_{K=0} = \langle \sigma(x) \rangle_{\mathcal{L}_\sigma} \quad \xrightarrow{\langle \sigma \rangle \neq 0} \quad m_f = -g \langle \sigma \rangle$$

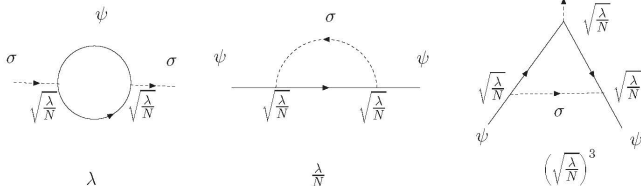
## 1/N展开的费曼图计算

$$\mathcal{L} = \underbrace{\bar{\psi}i\cancel{\partial}\psi}_{N \text{ 项}} + \frac{1}{2} \underbrace{g^2(\bar{\psi}\psi)^2}_{N^2 \text{ 项}} \xrightarrow{\text{为平衡动能与相互作用项}} g^2 N \equiv \lambda \quad \leftarrow \text{与 } N \text{ 无关}$$

存在分立对称性 对应QCD的手征对称性:  $\psi \rightarrow \gamma_5 \psi = e^{i\frac{\pi}{2}\gamma_5} \psi$   $\sigma \rightarrow -\sigma$   $\bar{\psi}\psi \rightarrow -\bar{\psi}\psi$

$$\mathcal{L}_\sigma = \bar{\psi}i\cancel{\partial}\psi + \sqrt{\frac{\lambda}{N}} \sigma \bar{\psi}\psi - \frac{1}{2} \sigma^2 \quad g \langle \bar{\psi}(x)\psi(x) \rangle_{\mathcal{L}} = \frac{1}{g} \langle \sigma(x) \rangle_{\mathcal{L}_\sigma}$$

一圈图:



所有两圈以上的一粒子不可约图都在  $N \rightarrow 0$  时趋于零, 在大  $N$  极限只须算一个一圈图!

## 1/N展开的路径积分计算

$$e^{iW[K]} = e^{-i\frac{K^2}{2}} \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i\int d^2x [\bar{\psi}(i\partial + g\sigma)\psi - \frac{1}{2}\sigma^2 + K\sigma]} = e^{-i\frac{K^2}{2}} \int \mathcal{D}\sigma e^{\text{Tr} \ln(i\partial + g\sigma) + i\int d^2x [-\frac{1}{2}\sigma^2 + K\sigma]}$$

$$e^{iW[K]} \stackrel{\sigma = \sqrt{N}\bar{\sigma}, K = \sqrt{N}\bar{K}}{=} e^{-iN\frac{\bar{K}^2}{2}} \int \mathcal{D}\bar{\sigma} e^{N\text{Tr}' \ln(i\partial + \sqrt{\lambda}\bar{\sigma}) + i\int d^2x N(-\frac{1}{2}\bar{\sigma}^2 + \bar{K}\bar{\sigma})} = e^{-iN\frac{\bar{K}^2}{2}} \int \mathcal{D}\bar{\sigma} e^{iNS[\bar{\sigma}, \bar{K}]}$$

$$S[\bar{\sigma}, \bar{K}] \equiv -i\text{Tr}' \ln(i\partial + \sqrt{\lambda}\bar{\sigma}) + \int d^2x (-\frac{1}{2}\bar{\sigma}^2 + \bar{K}\bar{\sigma})$$

应用Jackiw的路径积分算法:  $\frac{\partial W[K]}{\partial(\bar{\sigma})} = 0$

$$W[K] = \underbrace{-N\frac{\bar{K}^2}{2} + NS[\langle\bar{\sigma}\rangle, \bar{K}]}_{O(N)} + \underbrace{\frac{i}{2}\text{Tr} \ln \frac{\delta^2 S[\langle\bar{\sigma}\rangle, \bar{K}]}{\delta\langle\bar{\sigma}(x)\rangle\delta\langle\bar{\sigma}(y)\rangle}}_{O(\frac{1}{N})} + \bar{\Gamma}_2 \quad \bar{\Gamma}_2 = \sum_{n=2}^{\infty} \underbrace{\Gamma_n}_{O(\frac{1}{N^n})}$$

$\Gamma_n$  是以  $[\frac{\delta^2 S[\langle\bar{\sigma}\rangle, \bar{K}]}{\delta\langle\bar{\sigma}(x)\rangle\delta\langle\bar{\sigma}(y)\rangle}]^{-1}$  为传播子,  $I_{\text{int}}[\langle\bar{\sigma}\rangle, \tilde{\sigma}]$  为相互作用顶角的所有一粒子不可约n圈图

$I_{\text{int}}[\langle\bar{\sigma}\rangle, \tilde{\sigma}]$  是  $S[\langle\bar{\sigma}\rangle + \tilde{\sigma}, \bar{K}]$  中按  $\tilde{\sigma}$  幂次展开三次和三次以上项之和

## 渐进自由

$$\beta(g) = \mu \frac{\partial g}{\partial \mu} \Big|_{g_0, \Lambda} \quad \gamma_\sigma(g) = \frac{1}{2} \mu \frac{\partial}{\partial \mu} \ln Z_\sigma \Big|_{g_0, \Lambda} = \frac{1}{\sqrt{Z_\sigma}} \mu \frac{\partial}{\partial \mu} \sqrt{Z_\sigma} \Big|_{g_0, \Lambda} \quad \sigma_0 = \sqrt{Z_\sigma} \sigma$$

$$g_0 \bar{\psi}_0 \psi_0 \sigma_0 \stackrel{\text{费米子无修正}}{=} g_0 \bar{\psi} \psi \sigma_0 = g_0 \sqrt{Z_\sigma} \bar{\psi} \psi \sigma \Rightarrow g = g_0 \sqrt{Z_\sigma}$$

$$\beta(g) = \mu \frac{\partial g}{\partial \mu} \Big|_{g_0, \Lambda} = g_0 \mu \frac{\partial}{\partial \mu} \sqrt{Z_\sigma} \Big|_{g_0, \Lambda} = \frac{g}{\sqrt{Z_\sigma}} \mu \frac{\partial}{\partial \mu} \sqrt{Z_\sigma} \Big|_{g_0, \Lambda} = g \gamma_\sigma(g)$$

计算一圈 $\sigma$ 场自能:  $\Pi(p) = -g^2 N \int \frac{d^2 k}{(2\pi)^2} \frac{\text{tr}[\not{k}(\not{k} - \not{p})]}{k^2(k-p)^2} = -\lambda \int_0^1 d\alpha \int \frac{d^2 k}{(2\pi)^2} \frac{\text{tr}[\not{k}(\not{k} - \not{p})]}{[(k-p)^2 \alpha + k^2(1-\alpha)]^2}$

$$\stackrel{q \equiv k - \alpha p}{=} -\lambda \int_0^1 d\alpha \int \frac{d^2 q}{(2\pi)^2} \frac{\text{tr}\{(\not{q} + \alpha \not{p})[\not{q} + (\alpha - 1)\not{p}]\}}{[q^2 + \alpha(1-\alpha)p^2]^2} = \lambda \int_0^1 d\alpha \int \frac{i\pi d^2 q}{(2\pi)^2} \frac{2[q^2 + \alpha(1-\alpha)p^2] - 2(2\alpha - 1)q \cdot p}{[q^2 - \alpha(1-\alpha)p^2]^2}$$

$$= \frac{i\lambda}{2\pi} \int_0^1 d\alpha \left[ \ln \frac{-\Lambda^2}{\alpha(1-\alpha)p^2} - 2 \right] = \frac{i\lambda}{2\pi} \ln \frac{-\Lambda^2}{p^2} \quad \Pi_r = \Pi(p) - \Pi_c \quad D_0 = -i \quad D_r^{-1} = D_0^{-1} - \Pi_r$$

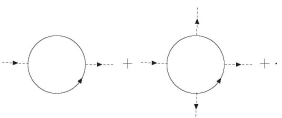
归一化条件:  $D_r(p^2 = -\mu^2) = -i \Rightarrow \Pi_c = \frac{\lambda}{2\pi} \ln \frac{\mu^2}{\Lambda^2} \Rightarrow D_r^{-1} = i \left[ 1 + \frac{\lambda}{2\pi} \ln \frac{-p^2}{\mu^2} \right]$

$$[\mu \frac{\partial}{\partial \mu} + \beta(g) \frac{\partial}{\partial g} - 2\gamma_\sigma(g)] D_r^{-1}(p) = 0 \Rightarrow \beta(g) = g\gamma_\sigma(g) = -\frac{g\lambda}{2\pi} \stackrel{\text{渐进自由}}{\Rightarrow} \bar{\lambda}(t) \stackrel{t = \frac{1}{2} \ln \frac{-p^2}{\mu^2}}{=} \frac{\lambda}{1 + \frac{\lambda t}{\pi}}$$

## 动力学对称性破缺

$$iS^{-1}(\hat{\sigma}; x, y) = \frac{\delta^2 S}{\delta\bar{\psi}(x)\delta\psi(y)} = (i\not{\partial} + g\hat{\sigma})\delta(x-y) \Rightarrow iS^{-1}(\hat{\sigma}, p) = -\not{p} + g\hat{\sigma}$$

$$V_{\text{eff}}(\hat{\sigma}) = \frac{1}{2}\sigma^2 + i \int \frac{d^2 p}{(2\pi)^2} \ln \frac{\det iS^{-1}(\hat{\sigma}, p)}{\det iS^{-1}(0, p)} = \frac{1}{2}\sigma^2 + iN \int \frac{d^2 p}{(2\pi)^2} \ln \begin{vmatrix} g\hat{\sigma} & -p_0 + p_1 \\ -p_0 - p_1 & g\hat{\sigma} \\ 0 & -p_0 + p_1 \\ -p_0 - p_1 & 0 \end{vmatrix}$$

$$= \frac{1}{2}\sigma^2 + iN \int \frac{d^2 p}{(2\pi)^2} \ln \left(1 - \frac{g^2 \hat{\sigma}^2}{p^2}\right)$$


$$= \frac{1}{2}\hat{\sigma}^2 + \frac{\lambda \hat{\sigma}^2}{4\pi} \left[ \ln \frac{g^2 \hat{\sigma}^2}{\Lambda^2} - 1 \right]$$

重整化：在有效势中加入抵消项  $-\frac{1}{2}C\hat{\sigma}^2$

$$1 = \left. \frac{\partial^2 V_{\text{eff}}}{\partial \hat{\sigma}^2} \right|_{\hat{\sigma}=M} \Rightarrow C = \frac{\lambda}{2\pi} \left[ \ln \frac{g^2 M^2}{\Lambda^2} + 2 \right]$$

$$V_{\text{eff}}(\hat{\sigma}) = \frac{1}{2}\hat{\sigma}^2 + \frac{\lambda \hat{\sigma}^2}{4\pi} \left[ \ln \frac{\hat{\sigma}^2}{M^2} - 3 \right]$$

$$0 = \left. \frac{dV_{\text{eff}}}{d\hat{\sigma}} \right|_{\hat{\sigma}=\langle\sigma\rangle} = \langle\sigma\rangle \left[ 1 + \frac{\lambda}{2\pi} \left( \ln \frac{\langle\sigma\rangle^2}{M^2} - 2 \right) \right]$$

$$\langle\sigma\rangle = \begin{cases} 0 \\ \pm M e^{1-\frac{\pi}{\lambda}} \end{cases} \Rightarrow \lambda = \frac{M=\langle\sigma\rangle}{\dots} = \pi$$

$$V_{\text{eff}}(0) = 0 \quad V_{\text{eff}}(\pm M e^{1-\frac{\pi}{\lambda}}) = -\frac{\lambda}{4\pi} M^2 e^{2-\frac{2\pi}{\lambda}}$$

考虑在Gross-Neveu模型中求 $\langle [\bar{\psi}(x)\psi(x)]^2 \rangle$ , 在原来拉氏量中插入积分

$$\int \mathcal{D}\sigma e^{-\frac{i}{2} \int d^2x [\sigma - \frac{g^2}{M} (\bar{\psi}\psi)^2]^2} \Rightarrow \mathcal{L}_\sigma = \bar{\psi}i\partial\psi - \frac{1}{2}\sigma^2 + \frac{g^2}{M} (\bar{\psi}\psi)^2 \sigma + \frac{1}{2}g^2 (\bar{\psi}\psi)^2 - \frac{1}{2} \frac{g^4}{M^2} (\bar{\psi}\psi)^4$$

出现了形式上不可重整的相互作用项, 但Gross-Neveu模型原本是可重整的

需要建立直接描述 $\langle [\bar{\psi}(x)\psi(x)]^2 \rangle$  的有效势理论

- ▶ Kuang, Li, Zhao, Commun. Theor. Phys. 3, 251(1984)
- ▶ He, Wang, Kuang, Z.Phys. C45,407(1990)
- ▶ He, Kuang, Z.Phys. C47,565(1990)

$$\begin{aligned} Z[K] &= \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i \int d^2x [\bar{\psi}(i\partial + g\sigma)\psi - \frac{1}{2}\sigma^2 + K\sigma]} \\ &= \int \mathcal{D}\psi \mathcal{D}\bar{\psi} \mathcal{D}\sigma e^{i \int d^2x [\bar{\psi}i\partial\psi - \frac{1}{2}(\sigma - g\bar{\psi}\psi - K)^2 + \frac{1}{2}g^2(\bar{\psi}\psi)^2 + \frac{1}{2}K^2]} \\ &= \int \mathcal{D}\psi \mathcal{D}\bar{\psi} e^{i \int d^2x [\bar{\psi}i\partial\psi + \frac{1}{2}g^2(\bar{\psi}\psi)^2 + Kg\bar{\psi}\psi + \frac{1}{2}K^2]} \end{aligned}$$

经验: 构造局域复合算符的有效势需要 加入纯外源项 !

## 如何决定纯外源项？

$$W[I, \bar{I}, K] = -i \ln Z[I, \bar{I}, K] \quad Z[I, \bar{I}, K] = \int \mathcal{D}\psi \mathcal{D}\bar{\psi} e^{i \int d^2x [\bar{\psi} i \not{\partial} \psi + \frac{1}{2} g^2 (\bar{\psi} \psi)^2 + \bar{I} \psi + \bar{\psi} I + K g \bar{\psi} \psi + P(K)]}$$

$$\frac{\delta W}{\delta \bar{I}} = \hat{\psi} \quad \frac{\delta W}{\delta I} = -\hat{\bar{\psi}} \quad \frac{\delta W}{\delta K} = g \hat{\bar{\psi}} \hat{\psi} + \Sigma \leftarrow \text{连接部分} \quad \hat{\psi} \Big|_{I=\bar{I}=0} = \hat{\bar{\psi}} \Big|_{I=\bar{I}=0} = 0$$

$$\frac{\delta^2 W}{\delta K^2} = -i \frac{\delta}{\delta K} Z^{-1} \frac{\delta Z}{\delta K} = -i \left( Z^{-1} \frac{\delta^2 Z}{\delta K^2} - Z^{-1} \frac{\delta Z}{\delta K} Z^{-1} \frac{\delta Z}{\delta K} \right) = -i Z^{-1} \frac{\delta^2 Z}{\delta K^2} \Big|_{\text{连接}} \dots \frac{\delta^n W}{\delta K^n} = -i Z^{-1} \frac{\delta^n Z}{\delta K^n} \Big|_{\text{连接}}$$

$$\text{自洽条件: } \frac{\delta^n W_c}{\delta K^n} \Big|_{I=\bar{I}=K=0} = 0 \quad n \geq 2$$

$$\text{经典方程: } g \bar{\psi}_{\text{cl}} [g \bar{\psi}_{\text{cl}} \psi_{\text{cl}} + K] = 0 \Rightarrow g \bar{\psi}_{\text{cl}} \psi_{\text{cl}} = -K$$

$$W_c[0, 0, K] = \int d^2x \left[ \frac{1}{2} g^2 (\bar{\psi}_{\text{cl}} \psi_{\text{cl}})^2 + K g \bar{\psi}_{\text{cl}} \psi_{\text{cl}} + P(K) \right] = \int d^2x \left[ -\frac{1}{2} K^2 + P(K) \right] \Rightarrow P(K) = \frac{1}{2} K^2$$

纯外源项由自洽条件决定！

直接一圈图计算：

$$W[I, \bar{I}, K] = -i \ln Z[I, \bar{I}, K] \quad Z[I, \bar{I}, K] = \int \mathcal{D}\psi \mathcal{D}\bar{\psi} e^{i \int d^2x [\bar{\psi} i \not{\partial} \psi + \frac{1}{2} g^2 (\bar{\psi} \psi)^2 + \bar{I} \psi + \bar{\psi} I + K g \bar{\psi} \psi + P(K)]}$$

$$W = W_c + W_1 \quad W_1 = -\frac{\lambda}{4\pi} \int d^2x F^2 (\ln \frac{g^2 F^2}{\Lambda^2} - 1) \quad F \equiv g \bar{\psi}_{cl} \psi_{cl} + K \quad \text{需加入抵消项:}$$

$$-\frac{1}{2} C_1 (g \bar{\psi}_{cl} \psi_{cl})^2 - C_2 g \bar{\psi}_{cl} \psi_{cl} K - \frac{1}{2} C_3 K^2 \quad \Gamma^{\text{部分}}[\psi_{cl}, \bar{\psi}_{cl}, K] = W[I, \bar{I}, K] - \int d^2x [\bar{I} \psi_{cl} + \bar{\psi}_{cl} I]$$

$$\text{归一化条件: } \left. \frac{\delta^4 \Gamma^{\text{部分}}}{\delta \bar{\psi}_{cl} \delta \psi_{cl} \delta \bar{\psi}_{cl} \delta \psi_{cl}} \right|_{\text{减除点}} = g^2 \quad \left. \frac{\delta^3 \Gamma^{\text{部分}}}{\delta \bar{\psi}_{cl} \delta \psi_{cl} \delta K} \right|_{\text{减除点}} = g \quad \left. \frac{\delta^2 \Gamma^{\text{部分}}}{\delta K^2} \right|_{\text{减除点}} = 1$$

$$C_1 = C_2 = C_3 = -\frac{\lambda}{2\pi} (\ln \frac{g^2 M^2}{\Lambda^2} + 2) \quad M \equiv F \Big|_{\text{减除点}}$$

$$W_1 = \int d^2x \left[ \frac{1}{2} (g \bar{\psi}_{cl} \psi_{cl})^2 + \bar{\psi}_{cl} I + \bar{I} \psi_{cl} + g \bar{\psi}_{cl} \psi_{cl} K + \frac{1}{2} K^2 - \frac{\lambda}{4\pi} F^2 (\ln \frac{F^2}{M^2} - 3) \right]$$

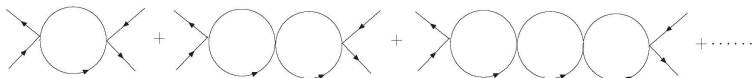
$$\Gamma[\hat{\psi}, \hat{\bar{\psi}}, \Sigma] = W[I, \bar{I}, K] - \int d^2x [\bar{I} \hat{\psi} + \hat{\bar{\psi}} I + K \Sigma] = V_{\text{eff}}[\hat{\psi}, \hat{\bar{\psi}}, \Sigma] \int d^2x$$

$$= \int d^2x \left[ \frac{1}{2} (g \hat{\bar{\psi}} \hat{\psi})^2 - \frac{1}{2} \Sigma^2 - \frac{\lambda}{4\pi} (g \hat{\bar{\psi}} \hat{\psi} + \Sigma)^2 \left[ \ln \frac{(g \hat{\bar{\psi}} \hat{\psi} + \Sigma)^2}{M^2} - 3 \right] \right] \stackrel{\Sigma \leftrightarrow \sigma}{=} V_{\text{eff}}[0, 0, \sigma] \text{回到上节结果!}$$



目前的结果只准到费米子的一圈图！

一圈图的结果被证明在大N极限下到任意阶圈图都严格成立的！



建立了类似Jackiw给出的一般计算规则——**两粒子不可约图**

在计算  $\langle \bar{\psi}\psi \rangle$  的同时也计算  $(\langle \bar{\psi}\psi \rangle)^2$

$$\text{引入外源项: } K_1 \bar{\psi}\psi + K_2 (\bar{\psi}\psi)^2 + P(K_1, K_2)$$

首次系统计算了 **四费米算符的真空凝聚**！

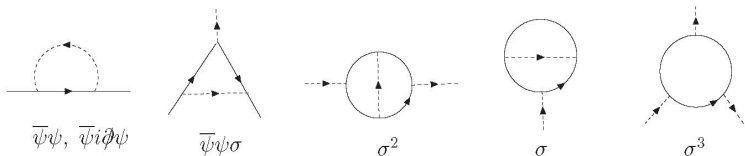
## D维( $2 < D < 4$ )四费米理论

D维四费米理论当 $D > 2$ 时在微扰论中是不可重整的！

但发现 $D = 3$ 的四费米理论在 $1/N$ 展开中是可重整的！

B.Rosenstein, B.Warr, and S.H.Park, Phys. Rev. Lett. 62, 1433(1989)

$$O\left(\frac{1}{N}\right)$$



理论具有对称性： $\bar{\psi}\psi \xrightarrow{\psi \rightarrow \gamma_5 \psi} -\bar{\psi}\psi$ ,  $\sigma \xrightarrow{\psi \rightarrow \gamma_5 \psi} -\sigma$

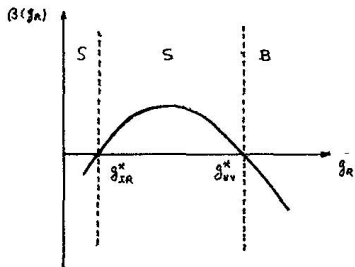
使得 $O\left(\frac{1}{N}\right)$ 六个图中只要计算方法不破坏对称性只有三个存在！动力学自发破缺不增加新发散！

剩下三个图在拉氏量中分别有对应的抵消项！此分析可以被推广到任意阶

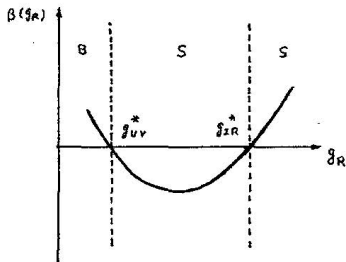
探索非微扰理论中的可重整性更一般维数的四费米理论在 $1/N$ 展开中可重整行为！

H.J.He, Y.P.Kuang, Q.Wang and Y.P.Yi, Phys. Rev. D45, 4610(1992)

探索 非微扰理论中的可重整性 更一般维数的四费米理论在 $1/N$ 展开中可重整行为！



(a)



(b)

理论存在非零的紫外固定点  $\lambda^* = \frac{(4\pi)^{D/2}(D-2)}{8(D-1)\Gamma(2-\frac{D}{2})} \left[ 1 + \frac{2^{D-3}(D-1)}{N} \right]$

$$\beta(\lambda) = (D-2)\lambda \left( 1 - \frac{\lambda}{\lambda^*} \right) \left[ 1 - \frac{1}{NDB \left( \frac{D}{2} - 1, 2 - \frac{D}{2} \right) B \left( \frac{D}{2}, \frac{D}{2} \right)} \right]$$

大的反常量纲:  $\gamma_{\bar{\psi}\psi}(\lambda^*) = D-2 + \frac{1}{NDB \left( \frac{D}{2} - 1, 2 - \frac{D}{2} \right) B \left( \frac{D}{2}, \frac{D}{2} \right)}$

$$B(p, q) \equiv \int_0^1 dt t^{p-1} (1-t)^{q-1}$$